

***SAFIR<sup>®</sup>***

***A software for modeling  
the behavior of structures  
subjected to the fire***

***Course by***

***Jean Marc Franssen & Thomas Gernay***



# ***Basic theory of the shell F.E.***

- 1) Degrees of freedom and local axes
- 2) Numerical integration
- 3) Material properties
- 4) Temperature distribution
- 5) Orientation of the rebars
- 6) Spurious modes
- 7) Output
- 8) Examples

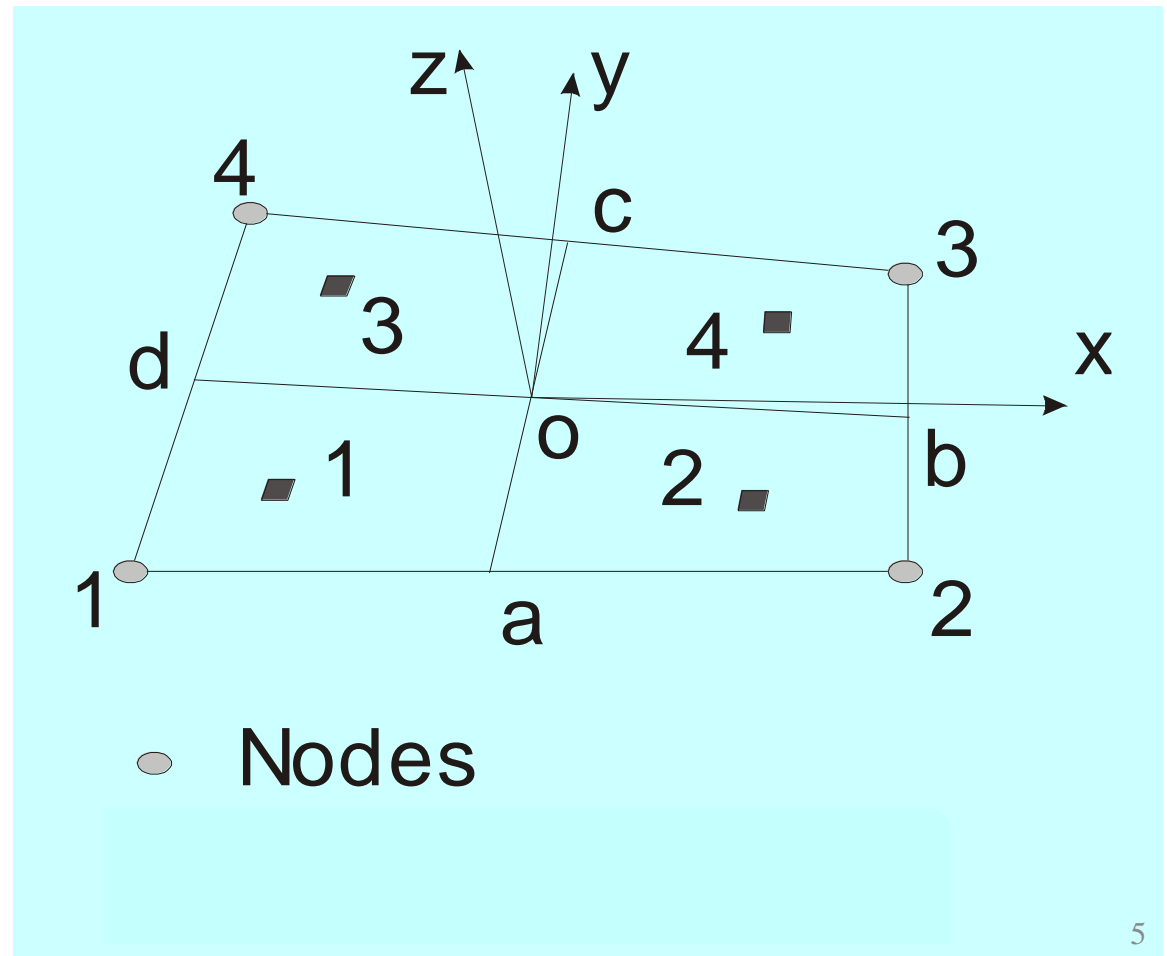
# Three steps in the structural fire design:

- 1. Define the fire (not made by SAFIR).*
- 2. Calculate the temperatures in the structure.*
- 3. Calculate the mechanical behaviour.*

- 1) Degrees of freedom and local axes
- 2) Numerical integration
- 3) Material properties
- 4) Temperature distribution
- 5) Orientation of the rebars
- 6) Spurious modes
- 7) Output
- 8) Examples

## The shell finite element

- ✓ 4 nodes
- ✓ Uniform thickness



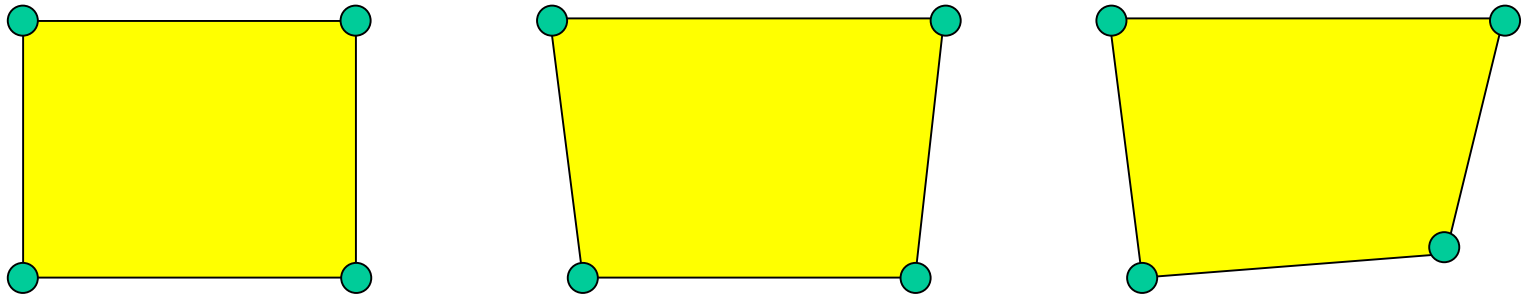
6 D.o.F. at each node of the shell elements:

3 translations

3 rotations.

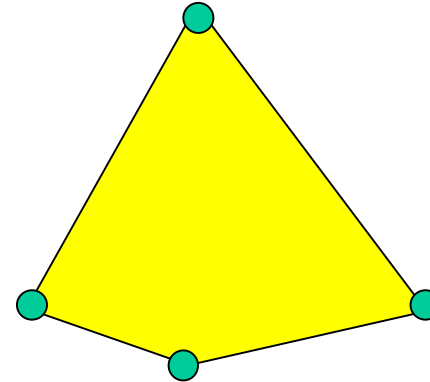
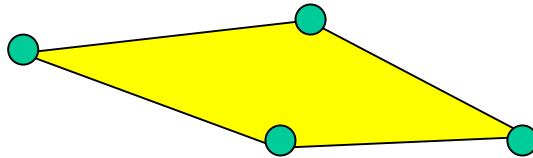
⇒ One node of the structure can be used:

- as the end node of a 3D beam element and
- as the node of a shell element and
- as the node of a truss element.

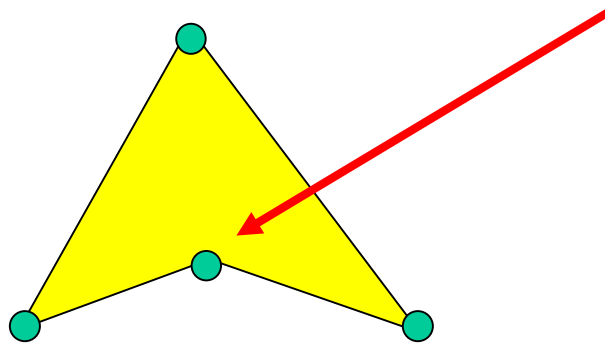


GEOMETRIES OK

NB: The 4 nodes need not be in the same plane  
(still, it is preferable not to distort too much out of plane)



GEOMETRIES not recommended



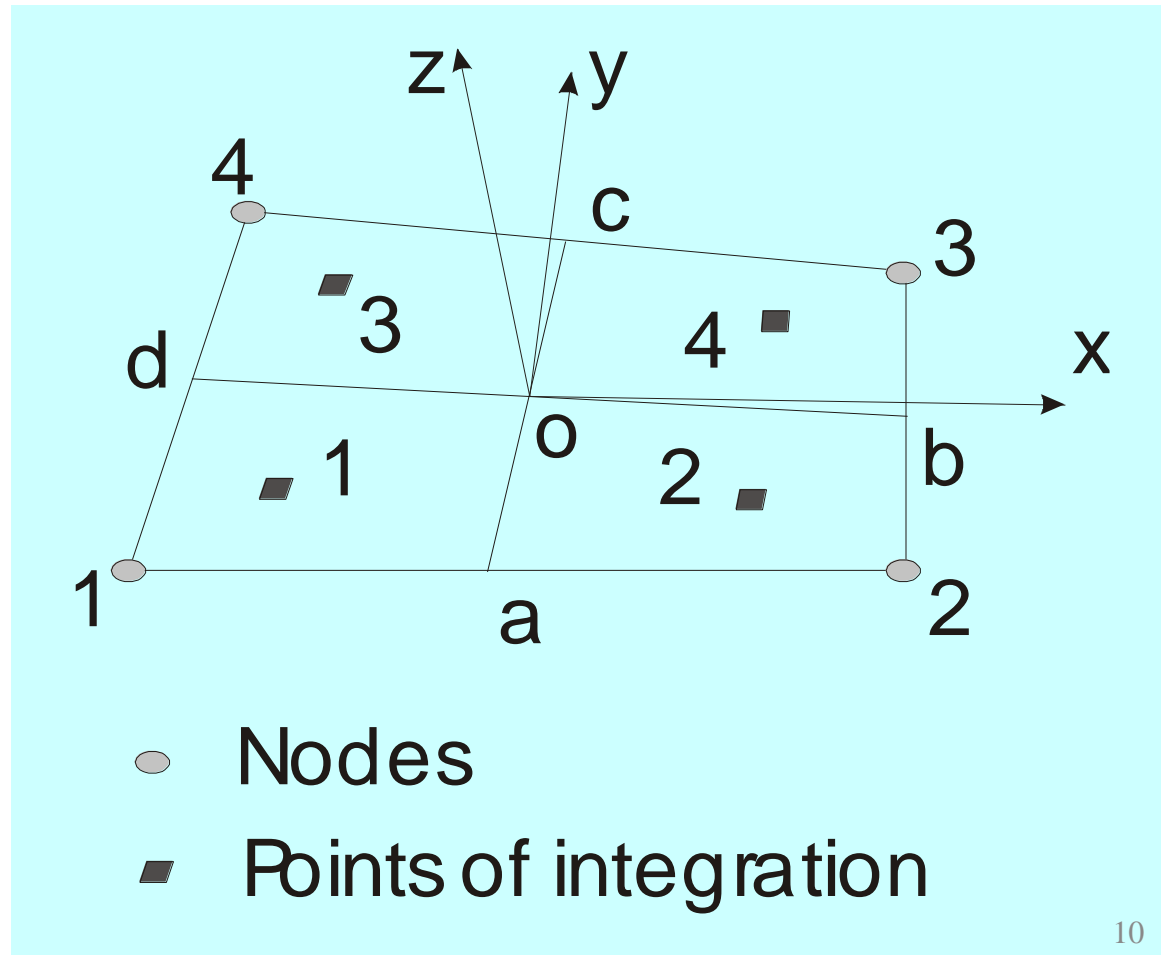
GEOMETRY not accepted



- 1) Degrees of freedom and local axes
- 2) Numerical integration**
- 3) Material properties
- 4) Temperature distribution
- 5) Orientation of the rebars
- 6) Spurious modes
- 7) Output
- 8) Examples

## The shell finite element

- ✓ 4 nodes
- ✓ Uniform thickness
- ✓ 4 points of integration on the thickness

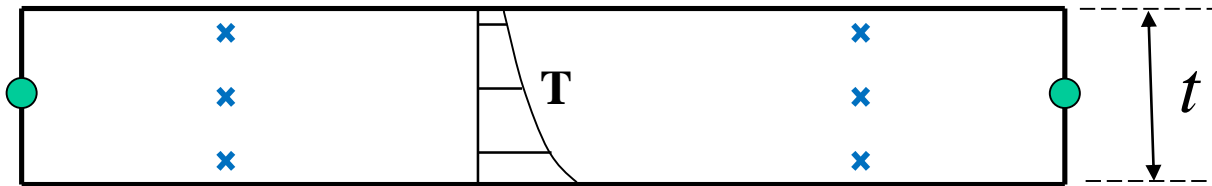


# The Shell Finite Element

NG integration points on the thickness  $t$

NG is chosen by the user, from 2 to 10.

Here, NG = 3

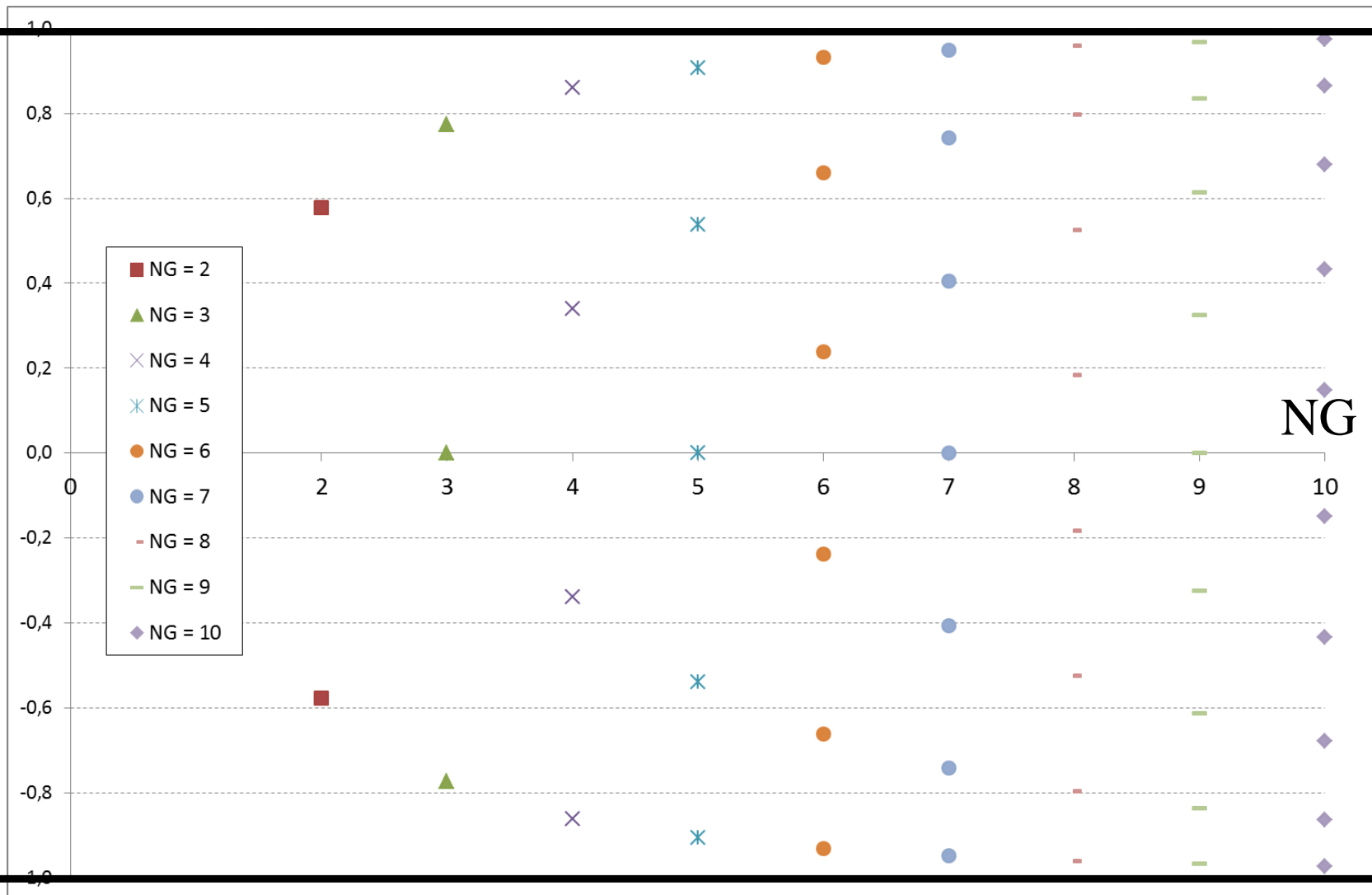


The temperature  $T$  varies on the thickness of the element.

$T$  does not vary in the plane of the element,  
except for localized fires (HASEMI, LOCAFI or CFD-SAFIR interaction).

Membrane behavior (steel plates):  $NG = 2$

Flexural behavior (concrete slabs):  $NG \uparrow\uparrow$  (max. = 10)



Position of the integration points on the thickness

- 1) Degrees of freedom and local axes
- 2) Numerical integration
- 3) Material properties**
- 4) Temperature distribution
- 5) Orientation of the rebars
- 6) Spurious modes
- 7) Output
- 8) Examples

## Materials:

### ➤ Matrix of the element

STEELEC32D (plane stress, very stable)

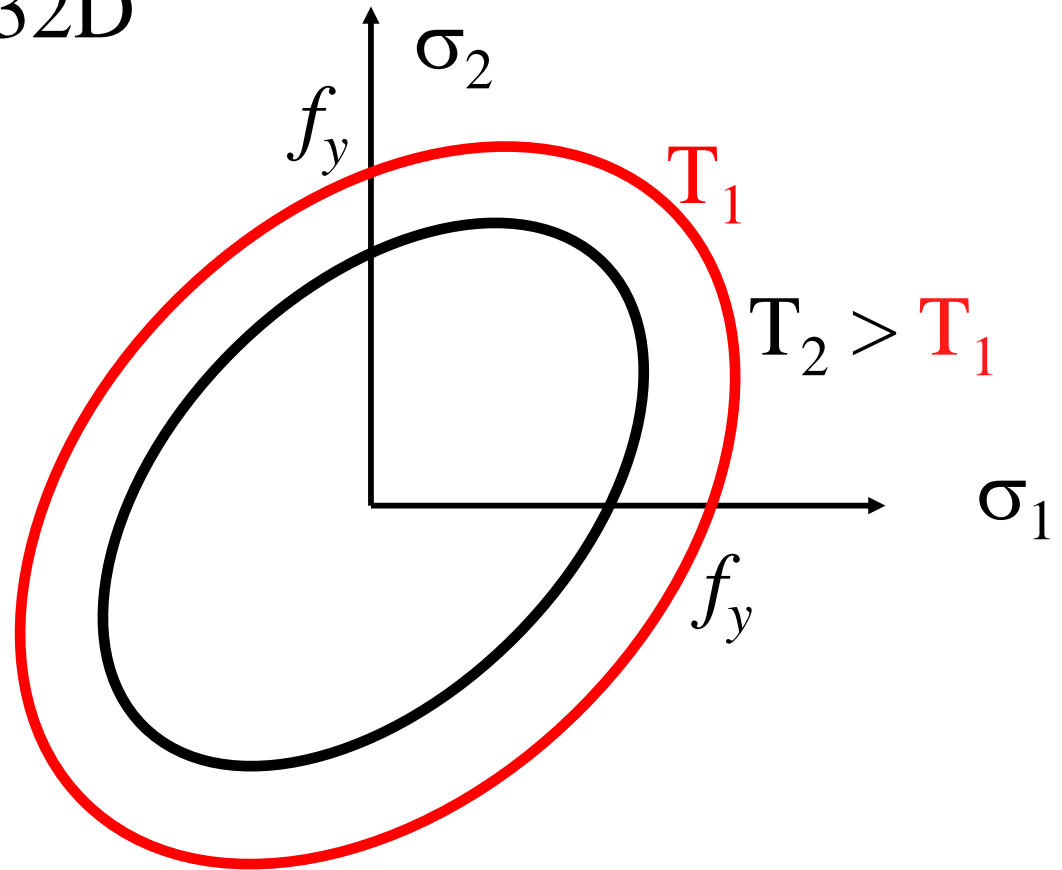
SILCOETC2D & CALCOETC2D (plane stress, stable)

$\nu$   $f_c$   $f_t$  0.0025 0.25 0.19 0.3 4000.

### ➤ Eventual rebars

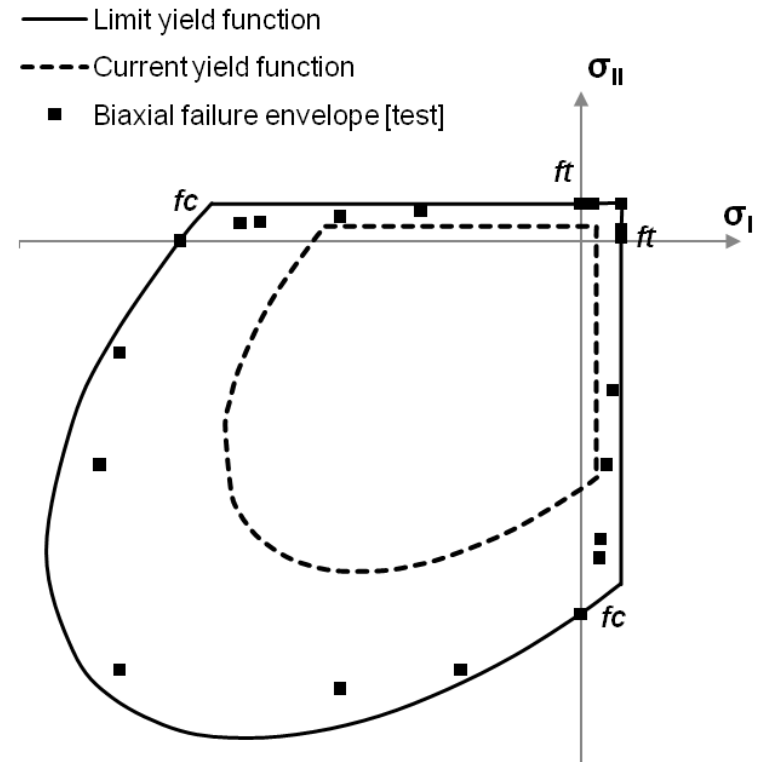
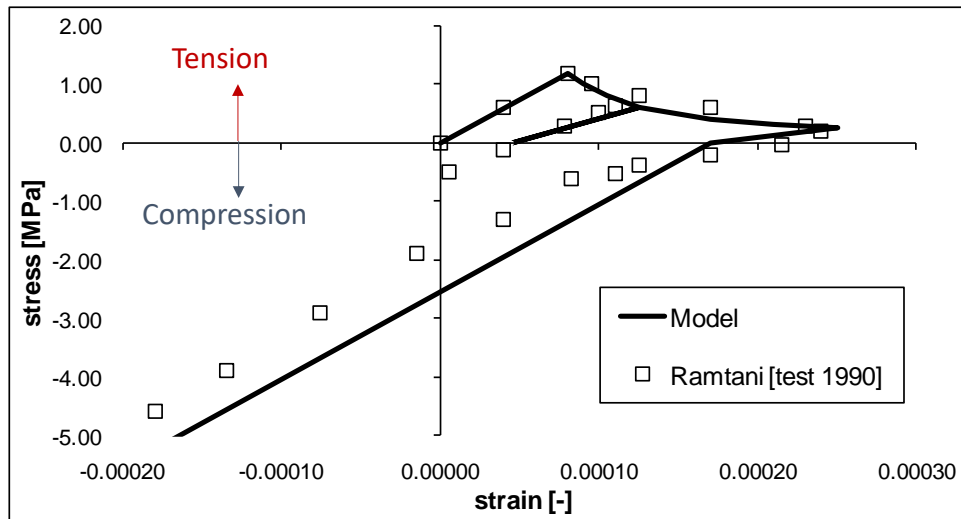
STEELEC2EN (uniaxial)

# STEELEC32D



- Associated plasticity
- Von Mises yield surface
- Isotropic hardening (same laws as EN 1993-1-2)

# SILCOETC2D & CALCOETC2D



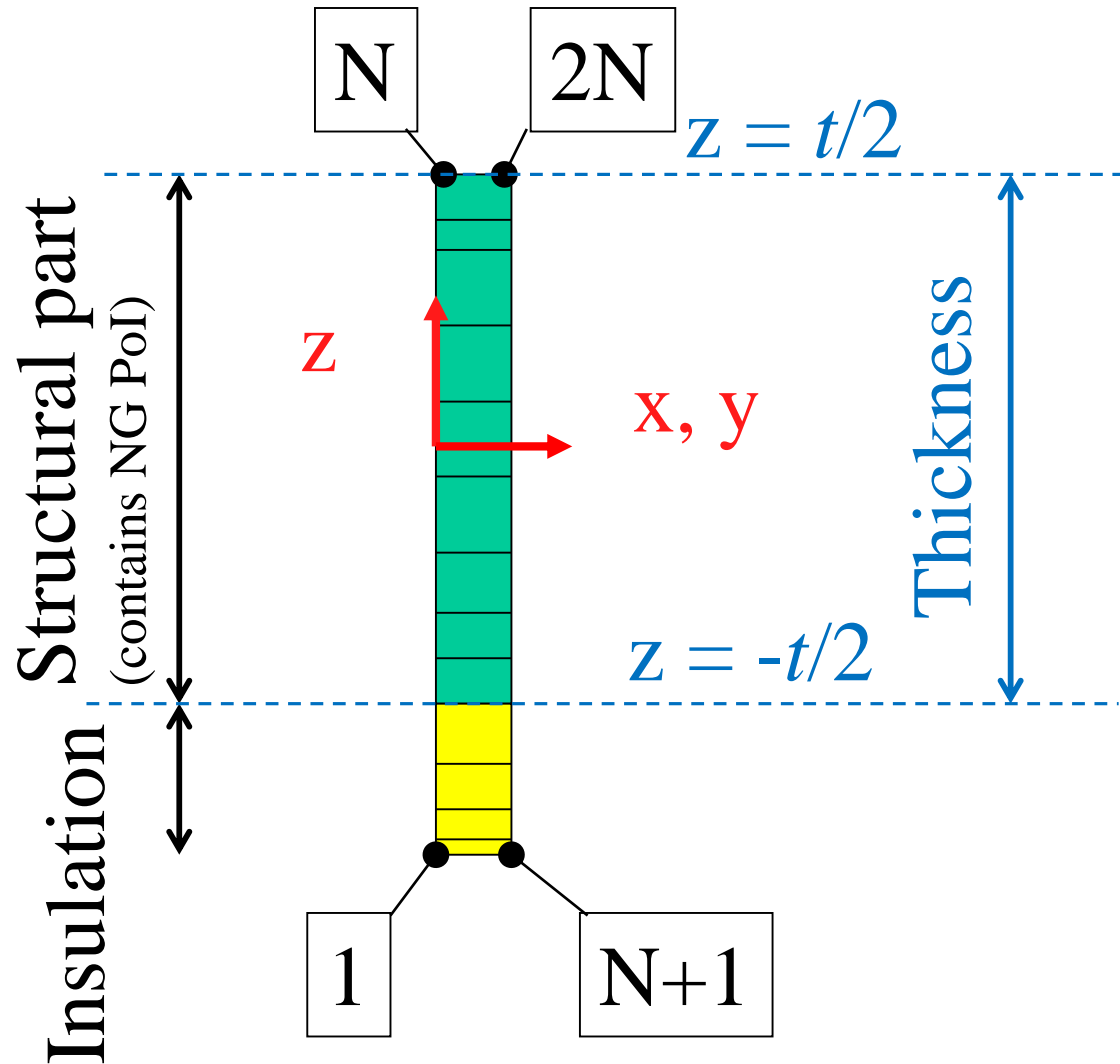
- Plastic-Damage model
- Multi-surface yield criterion: Drucker Prager - Rankine
- Damage tensor with crack closure

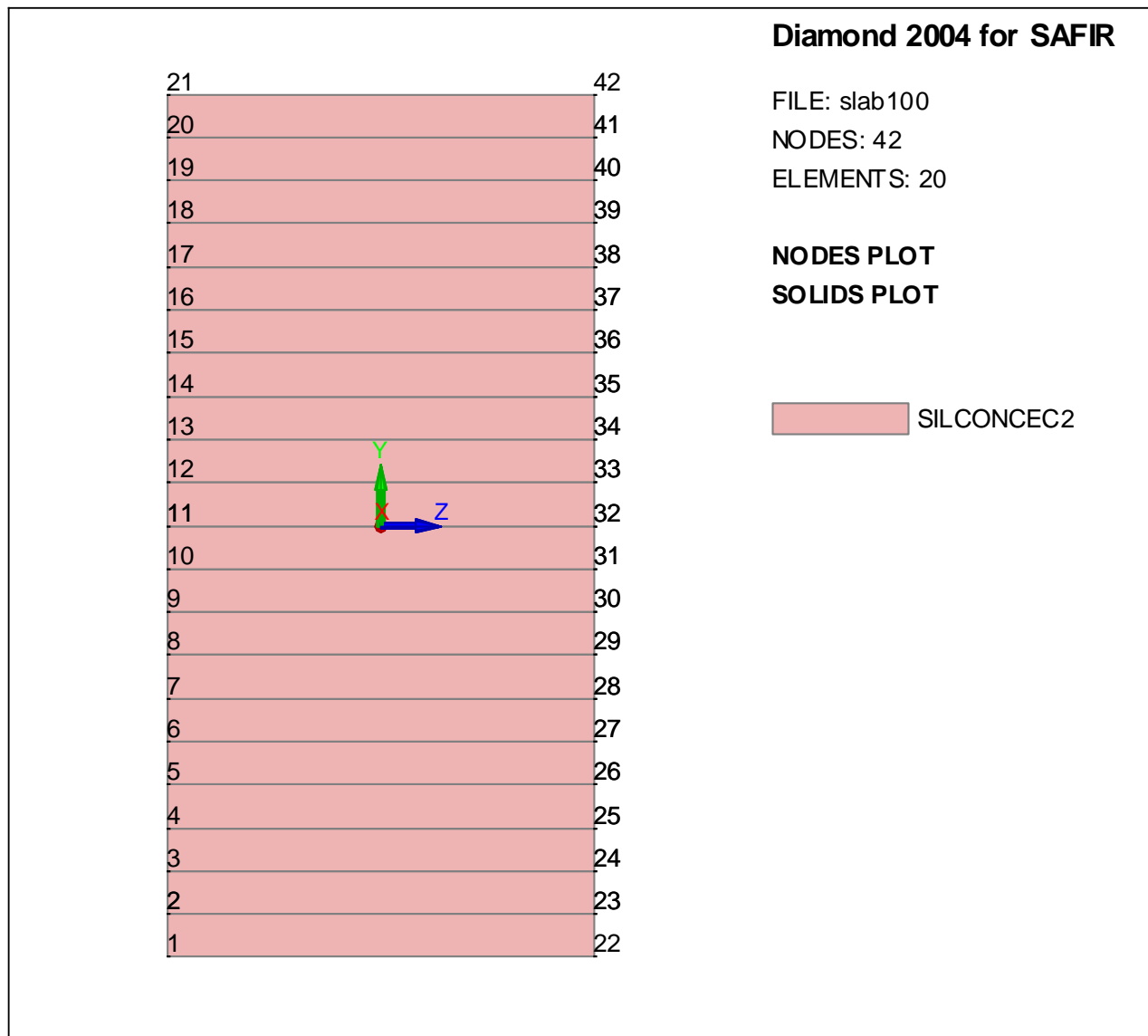


- 1) Degrees of freedom and local axes
- 2) Numerical integration
- 3) Material properties
- 4) Temperature distribution**
- 5) Orientation of the rebars
- 6) Spurious modes
- 7) Output
- 8) Examples

# Temperature distribution: 1D (2D)

Command MAKE.TSH will write the temperatures in a file « filename.tsh ».





Example of a mesh for a shell element without thermal protection.  
Note: the width of the model is not relevant.

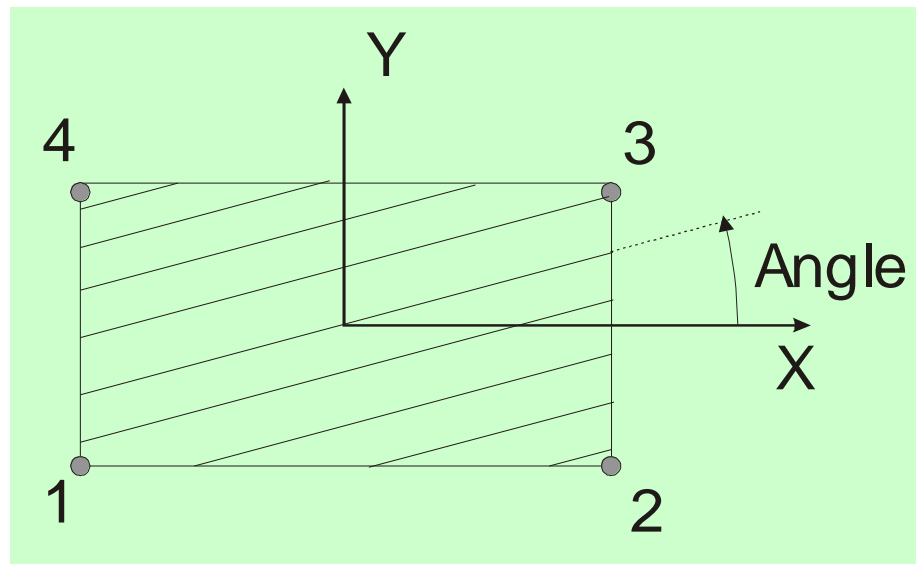
- 1) Degrees of freedom and local axes
- 2) Numerical integration
- 3) Material properties
- 4) Temperature distribution
- 5) Orientation of the rebars**
- 6) Spurious modes
- 7) Output
- 8) Examples

Different layers of rebars can be present in the element. The rebar layers are horizontal (i.e. parallel to the local  $x, y$  plane). The rebars are uniformly distributed (layered rebars). Each layer is defined by:

- it's local vertical coordinate  $z$  in the element (this level must not necessarily coincide neither with the position of a point of integration on the thickness, nor with a position where the temperature has been calculated. Linear interpolations are made);
- it's cross section per unit length of width ( $m^2/m$  for example);
- it's material number; and
- the angle between the direction of the rebars and the local  $x$  axis..

Assumptions for rebar elements are:

- the cross section of the rebar is not subtracted from the plane section of the element. This means that, in a reinforced concrete slab, steel and concrete are supposed to be simultaneously present at the location of the bars,
- the bars resist only axial direction actions. This means that a mesh of perpendicular rebars does not resist shear by itself.



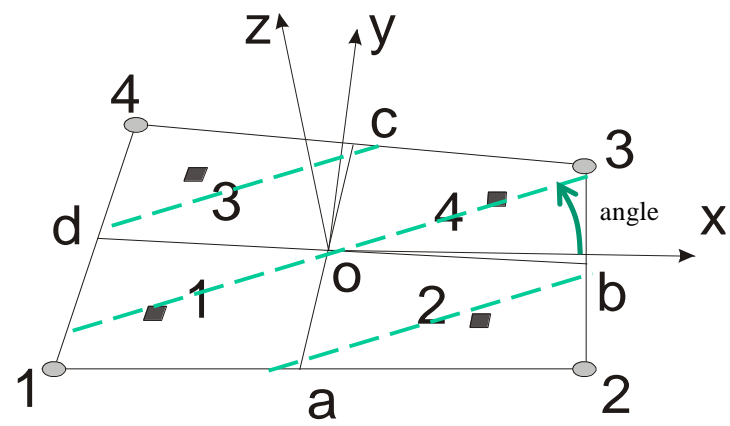
In fact, for each bar layer, there are two methods to give the orientation of the bars in the plane of the element.

Method 1: with respect to the local system of coordinates of each element.

1 card.

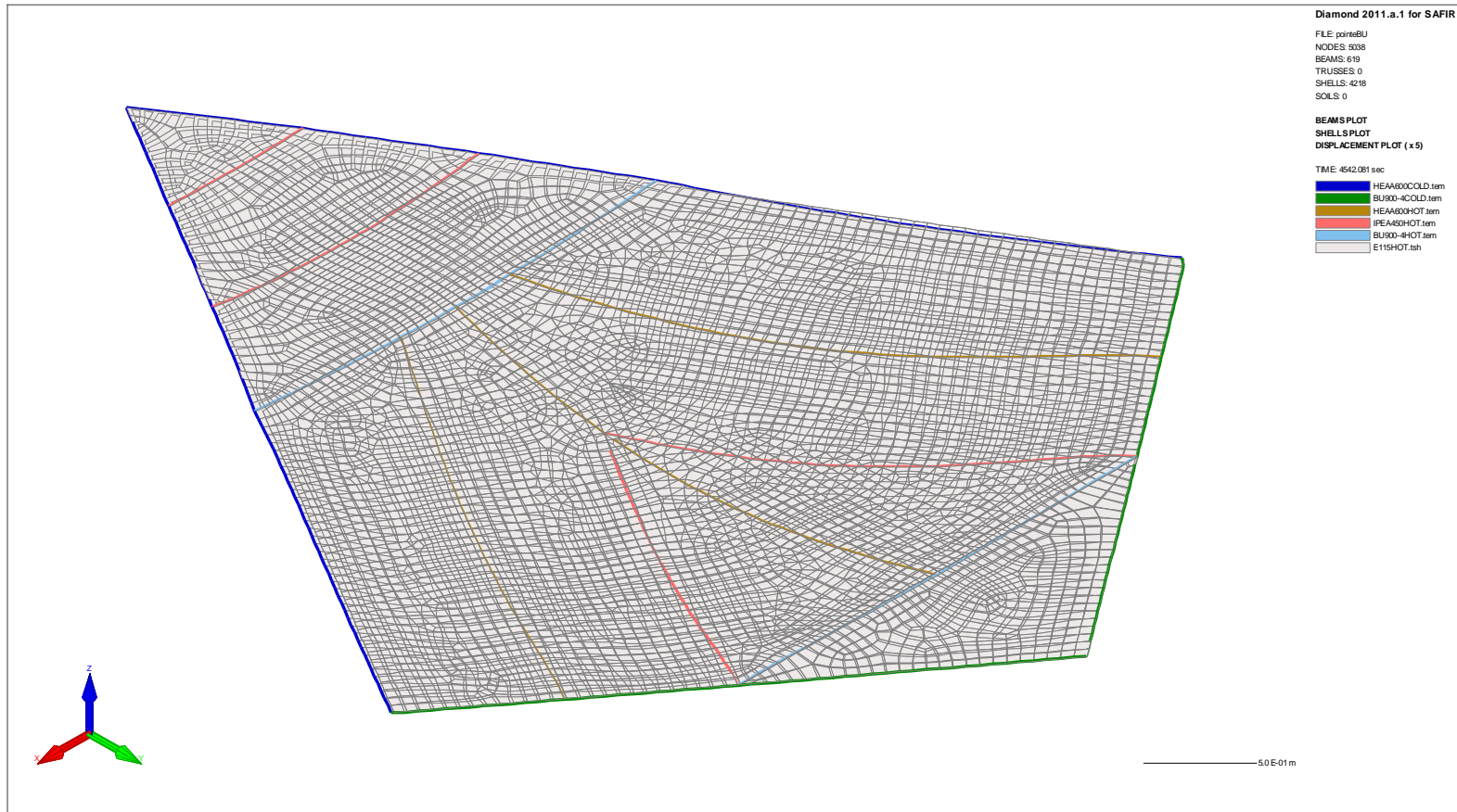
- "ANGLE"

- **angle**                      Angle in degrees between the local x axis and the layer of rebars, see Figure in which the bars of the layer are represented by dotted lines. This angle cannot be smaller than  $-180^\circ$ .



- Nodes
- Points of integration

This method is not appropriate in unstructured meshes because the local system of coordinates is different in all elements.



Japan Tobacco Intl, Geneva  
Model: Ingeni (courtesy Lorenzo Lelli)



**Method 2:** with respect to the global system of coordinates of the structure.

**1 card.**

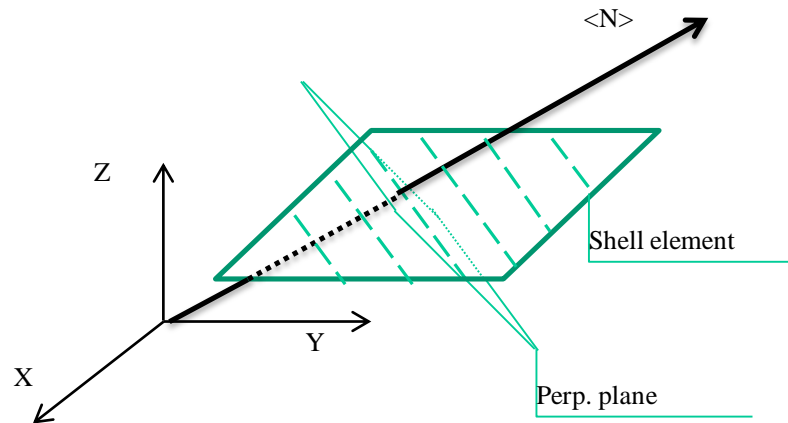
- "NORMAL"
- $N_1$
- $N_2$
- $N_3$

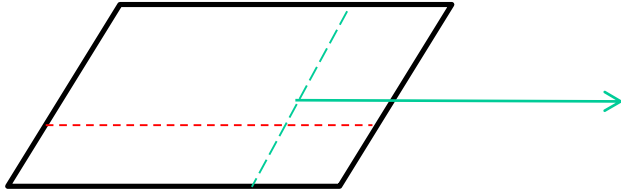
$\langle N_1 ; N_2 ; N_3 \rangle$  is a vector in the global system of coordinates of the structure. The norm of the vector does not have to be 1.

This vector is used to define the position of the bar layers in the shell elements with respect to the global system of coordinates according to the following technique, see Figure.

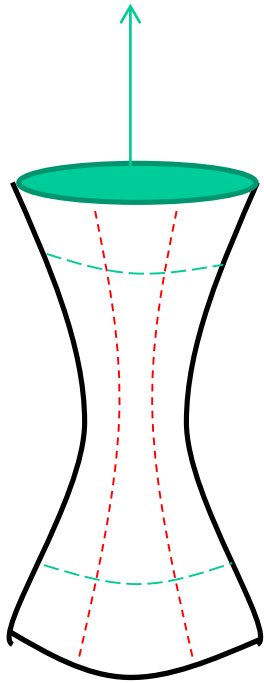
The bars have the orientation of the line which is the intersection between the shell element and a plane that is perpendicular to the normal.

If the norm of the vector is 0, then the orientation of this bar layer is perpendicular, in each element, to the previous bar layer (not possible for bar layer 1).

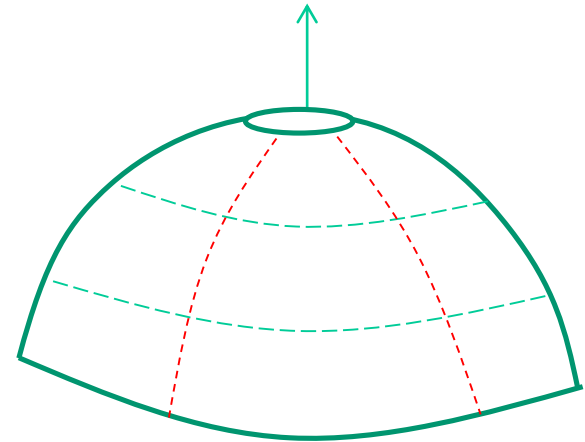




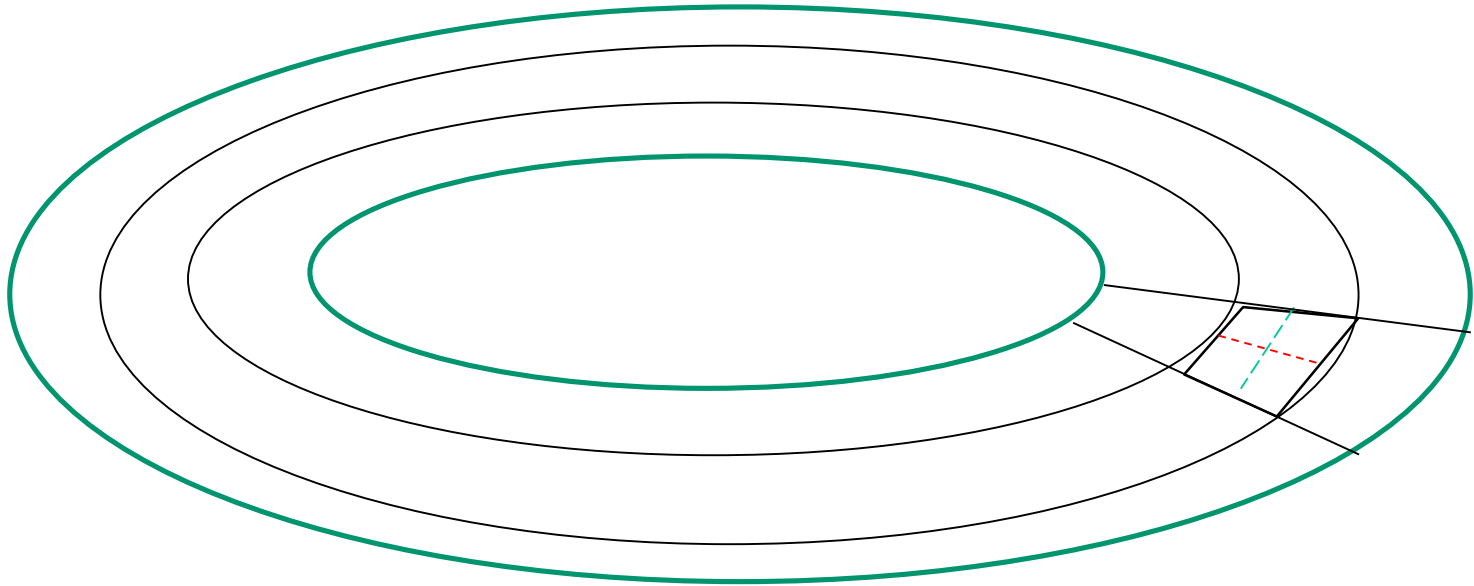
**Figure 3: bars in a plate.**  
 Use method 2 if the  
 mesh is unstructured



**Figure 4: bars in a hyperbolic paraboloid**  
 Method 2



**Figure 5: bars in a dome**  
 Method 2



**Figure 6: bars in a circular ring**

**Method 1**

ACKNOWLEDGEMENT

DEVELOPMENT OF THE SECOND METHOD HAS BEEN SUPPORTED  
BY « HOLMES FIRE »

The information about the re-bars of the shells (section, vertical position, orientation, number of the material) have to be entered by the user at the beginning of the file xxx.TSH that gives the temperatures for the relevant section type.

10 cm thick slab

! Comment lines

2 layers of re-bars

! 1 blank line

THICKNESS 0.10 meters

! General information

MATERIAL 1

REBARS 2 layers

MATERIAL 2

! Bar layer 1

SECTION 257e-6 m<sup>2</sup>/m

LEVEL -0.030 m

ANGLE 0. degree

MATERIAL 2

! Bar layer 2

SECTION 257e-6 m<sup>2</sup>/m

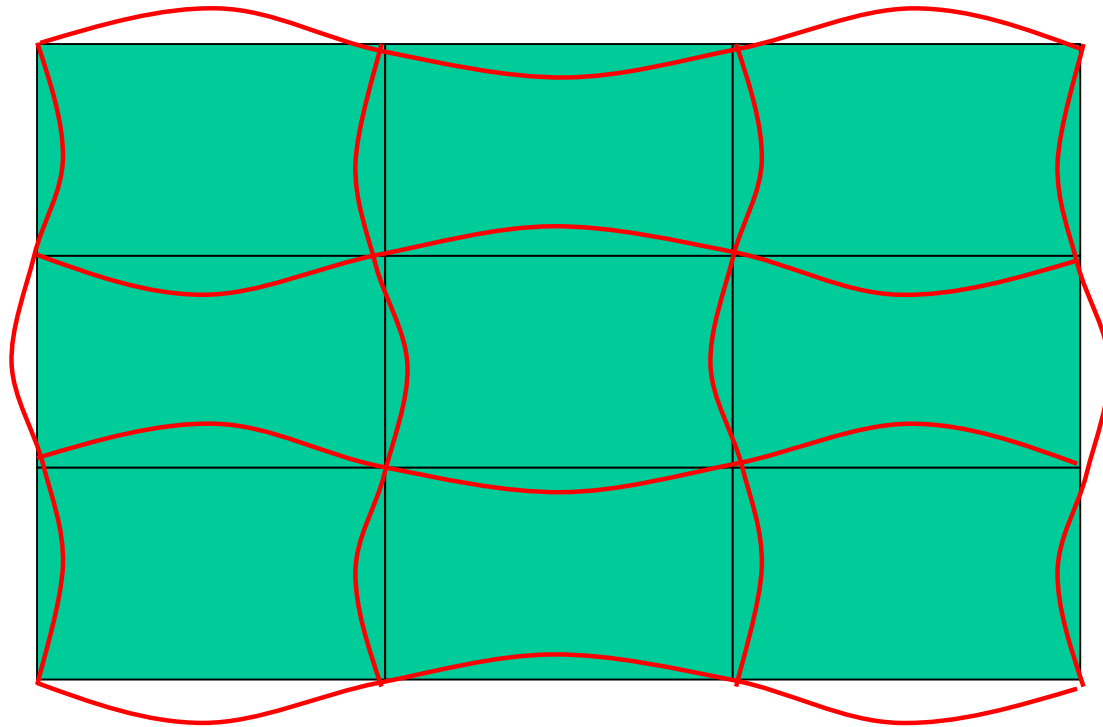
LEVEL -0.025 m

ANGLE 90. degrees

HOT

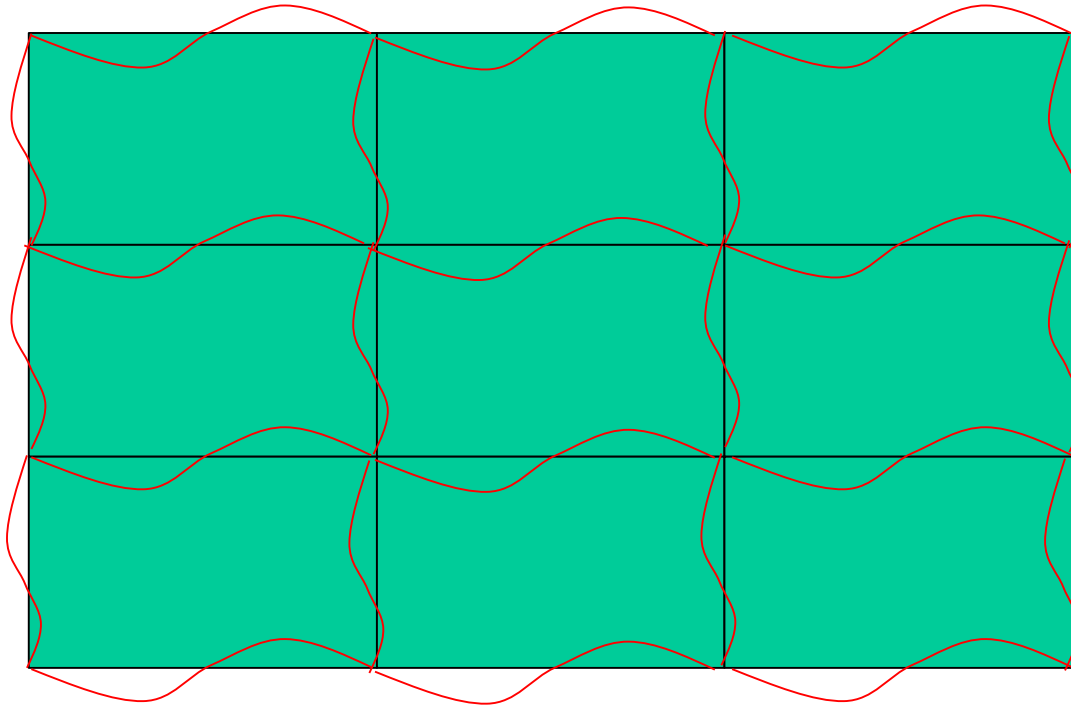
- 1) Degrees of freedom and local axes
- 2) Numerical integration
- 3) Material properties
- 4) Temperature distribution
- 5) Orientation of the rebars
- 6) Spurious modes**
- 7) Output
- 8) Examples

# Possibility of spurious mode 1 in perfectly regular meshes



Deformation with no energy activated in the  
four PoI of each element

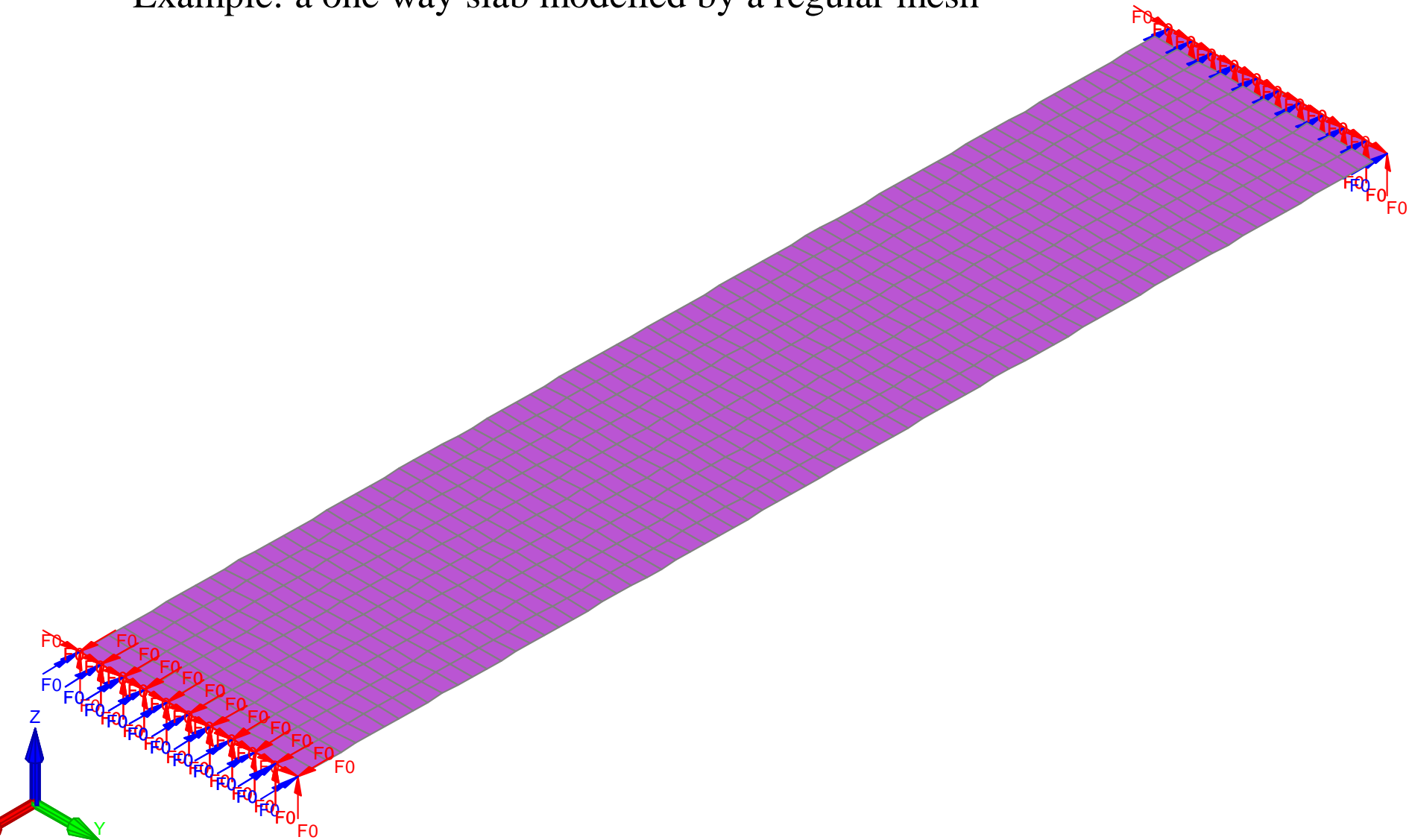
## Possibility of spurious mode 2 in perfectly regular meshes



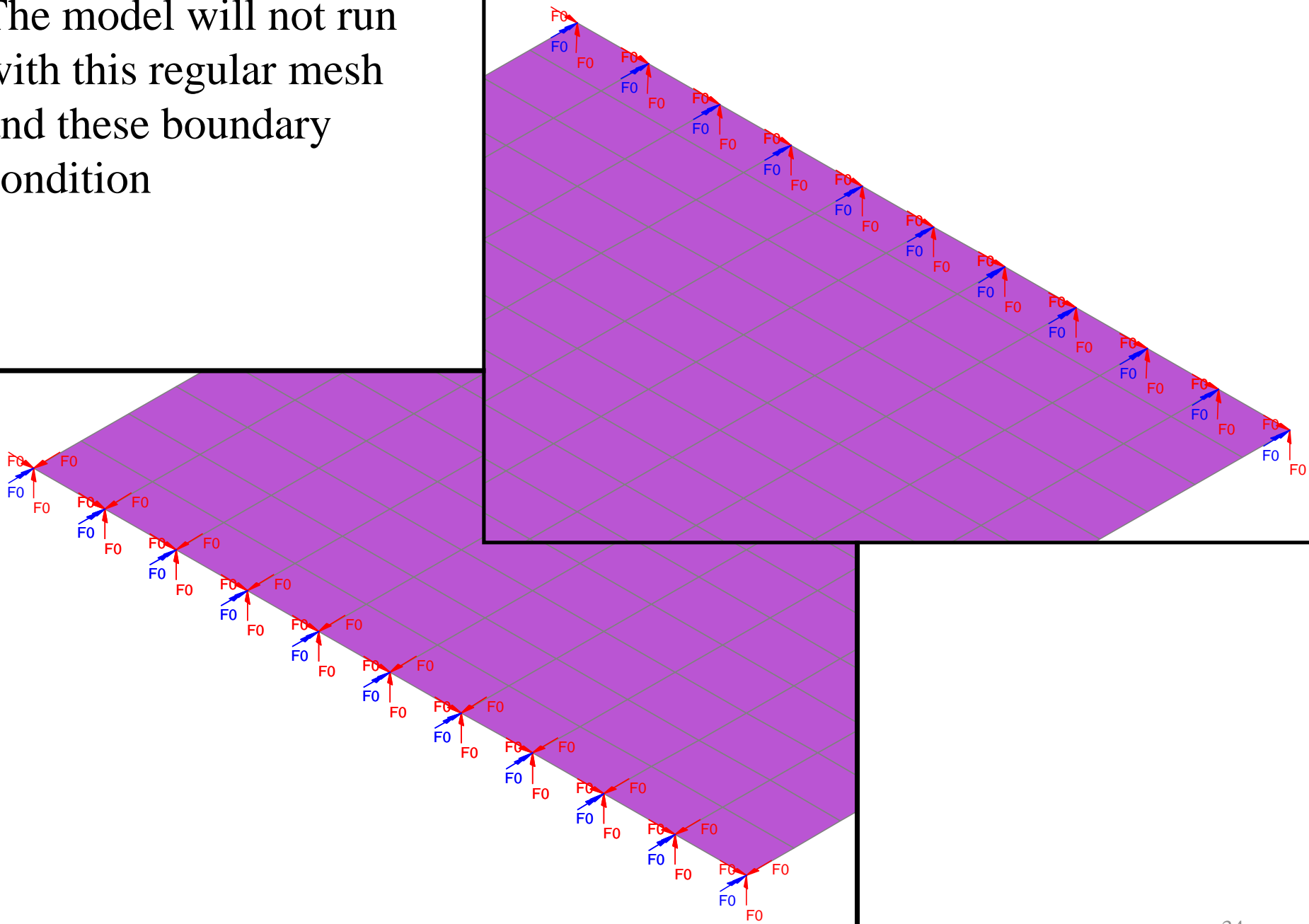
Deformation with no energy activated in the  
four PoI of each element



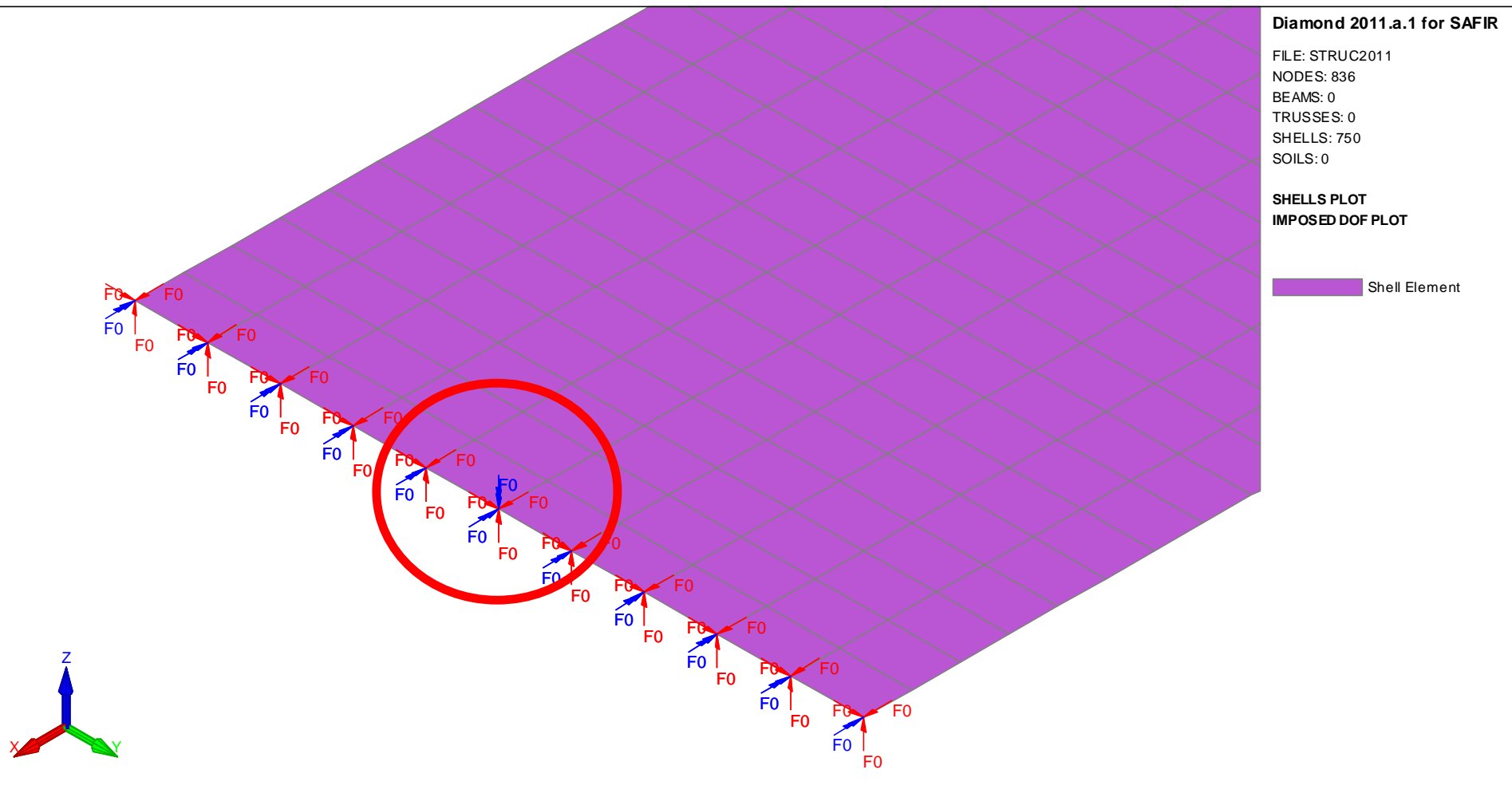
Example: a one way slab modelled by a regular mesh



The model will not run  
with this regular mesh  
and these boundary  
condition



# One possible solution



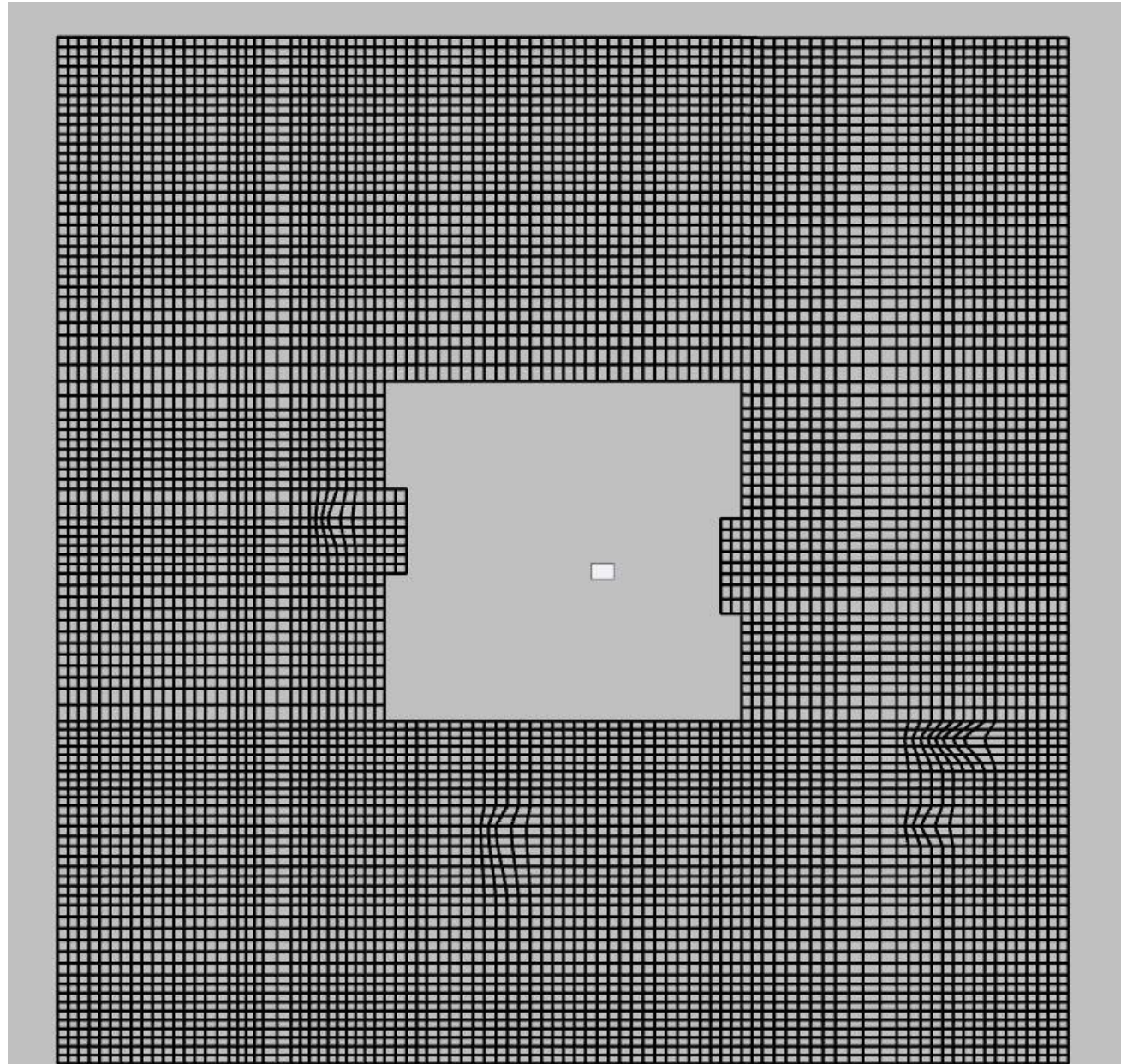
In this concrete slab, the mesh is « nearly » regular.

The model will run even if no rotation around  $z$  is fixed.

Yet, the rotations around  $z$  of all nodes increase as 0, +0.1, -0.2, +0.4, -0.8, until several radians !

This indicates a very low stiffness against spurious mode 2

Fixing the rotation around  $z$  at one node keeps all rotations more realistic.



- 1) Degrees of freedom and local axes
- 2) Numerical integration
- 3) Material properties
- 4) Temperature distribution
- 5) Orientation of the rebars
- 6) Spurious modes
- 7) Output**
- 8) Examples

# What can be printed about the material behavior?

PRNSIGMASH 1

## Strains and Stresses

- in the material of the shell [N/mm<sup>2</sup>]
- in the material of the eventual re-bars

PRNSIGMASH

is equivalent to

PRNSIGMASH in all shell elements

SHELL:	1, SURF: 1, THICK: 1	ex: -0.000002	ey: 0.000011	exy: 0.000000
SHELL:	1, SURF: 1, THICK: 1	Sx: 0.30	Sy: 2.40	Sxy: -0.04
SHELL:	1, SURF: 1, THICK: 2	ex: -0.000002	ey: 0.000011	exy: -0.000001
SHELL:	1, SURF: 1, THICK: 2	Sx: 0.28	Sy: 2.29	Sxy: -0.04
SHELL:	1, SURF: 1, THICK: 3	ex: -0.000002	ey: 0.000010	exy: -0.000001
SHELL:	1, SURF: 1, THICK: 3	Sx: 0.26	Sy: 2.11	Sxy: -0.05
SHELL:	1, SURF: 1, THICK: 4	ex: -0.000001	ey: 0.000009	exy: -0.000001
SHELL:	1, SURF: 1, THICK: 4	Sx: 0.22	Sy: 1.88	Sxy: -0.06
SHELL:	1, SURF: 1, THICK: 5	ex: -0.000001	ey: 0.000008	exy: -0.000001
SHELL:	1, SURF: 1, THICK: 5	Sx: 0.18	Sy: 1.64	Sxy: -0.07
SHELL:	1, SURF: 1, THICK: 6	ex: -0.000001	ey: 0.000007	exy: -0.000001
SHELL:	1, SURF: 1, THICK: 6	Sx: 0.14	Sy: 1.41	Sxy: -0.08

# What can be printed about the material behavior?

PRNNXSHELL

$N_x$ ,  $N_y$ ,  $N_{xy}$  [in kN/m] +  $N_1$ ,  $N_2$  and  $\alpha$  (with respect to the local axis  $x$ )

in the 4 integr. pts in the plane, for all shell elements

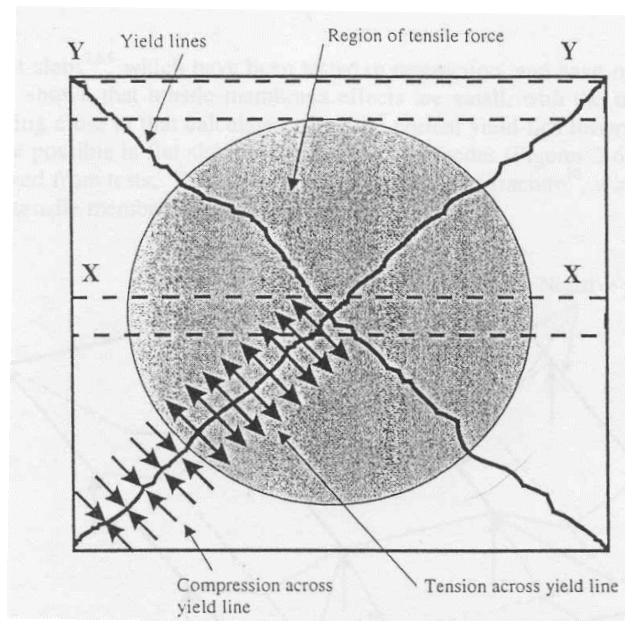
$$N_x = \int_{-t/2}^{t/2} \sigma_{xx} dt + \sum_{bars} \sigma_{x,i} A_i$$



# Membrane action in a concrete slab

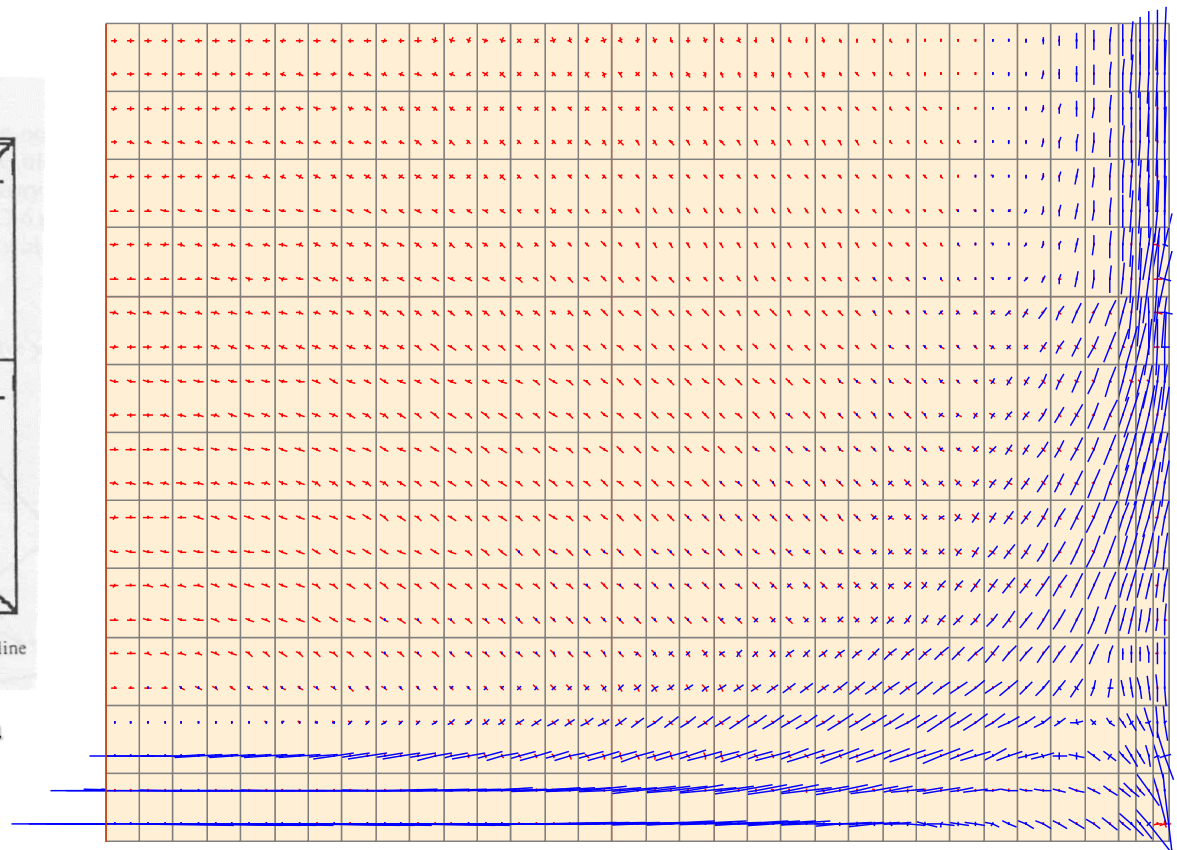
## *Membrane*

## *stresses*



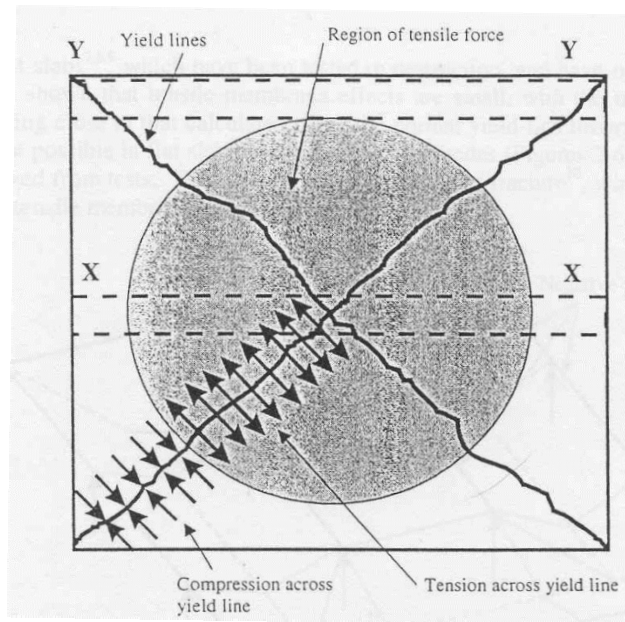
In-plane membranes forces in a slab with no in-plane restraint

C. Bailey (2000)



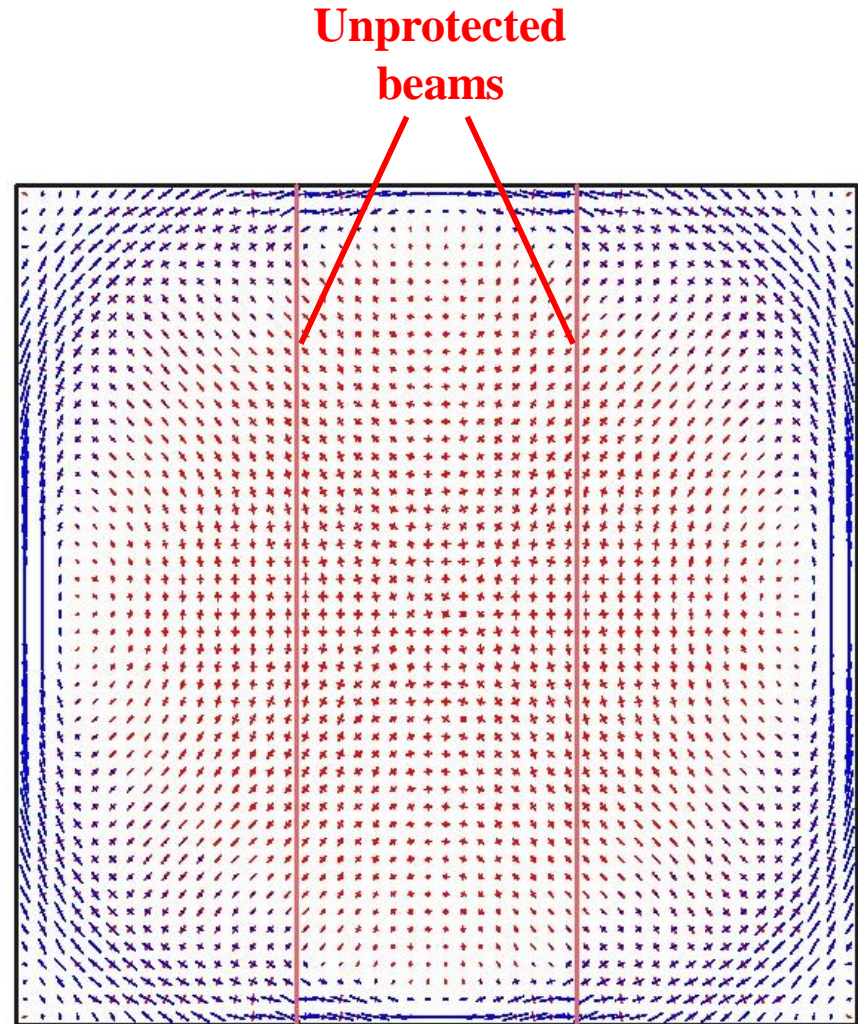
# Membrane action in a concrete slab

## *Membrane stresses*



In-plane membrane forces in a slab with no in-plane restraint

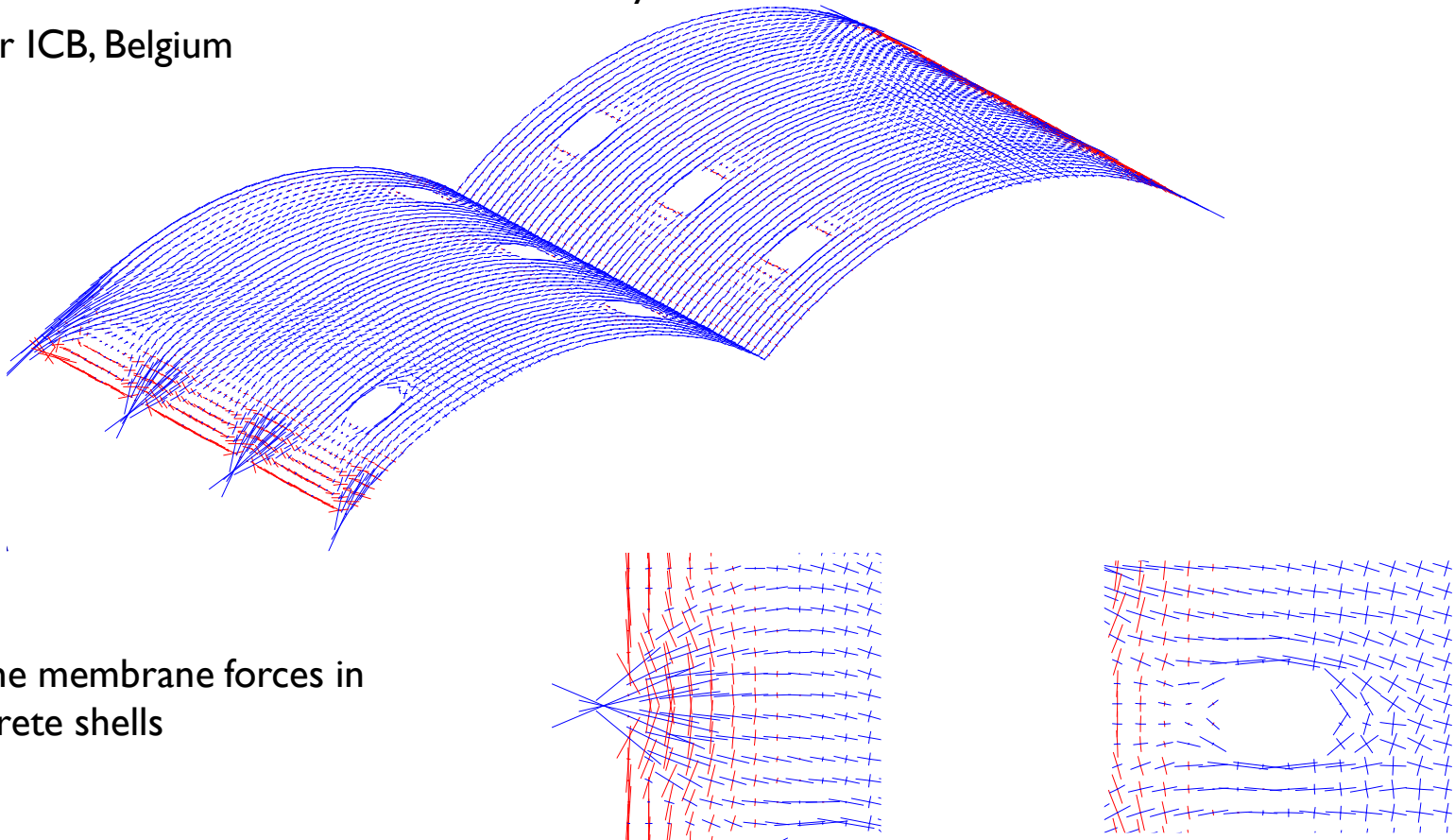
C. Bailey (2000)



# Membrane forces in a shell

3D mechanical calculation – Structural fire analysis of an arched reinforced concrete roof

Study for ICB, Belgium



Plot of the membrane forces in the concrete shells

SHELL:	1	Surf: 1	Nx:	2.12	Ny:	18.83	Nxy:	-0.72	N1:	18.86	N2:	2.09	angle:	-87.5°
SHELL:	1	Surf: 2	Nx:	2.32	Ny:	19.54	Nxy:	-0.92	N1:	19.59	N2:	2.27	angle:	-86.9°
SHELL:	1	Surf: 3	Nx:	-0.81	Ny:	18.01	Nxy:	-0.80	N1:	18.04	N2:	-0.85	angle:	-87.6°
SHELL:	1	Surf: 4	Nx:	-0.62	Ny:	18.71	Nxy:	-1.00	N1:	18.77	N2:	-0.67	angle:	-87.0°
SHELL:	2	Surf: 1	Nx:	2.31	Ny:	20.33	Nxy:	-1.75	N1:	20.49	N2:	2.15	angle:	-84.5°
SHELL:	2	Surf: 2	Nx:	2.78	Ny:	21.97	Nxy:	-2.97	N1:	22.42	N2:	2.33	angle:	-81.4°
SHELL:	2	Surf: 3	Nx:	-0.94	Ny:	19.42	Nxy:	-1.86	N1:	19.58	N2:	-1.11	angle:	-84.8°
SHELL:	2	Surf: 4	Nx:	-0.48	Ny:	21.06	Nxy:	-3.08	N1:	21.49	N2:	-0.91	angle:	-82.0°

# What can be printed about the material behavior?

PRNMXSHELL

$M_x$ ,  $M_y$ ,  $M_{xy}$  [in kNm/m] +  $M_1$ ,  $M_2$  and  $\alpha$   
in the 4 integr. pts in the plane, for all shell elements

$$M_x = \int_{-t/2}^{t/2} \sigma_{xx} z \, dz + \sum_{nbars} \sigma_{x,i} z_i A_i$$

SHELL:	1	Surf: 1	Mx:	0.00	My:	-0.01	Mxy:	0.00	M1:	0.00	M2:	-0.01	angle:	-3.2°
SHELL:	1	Surf: 2	Mx:	0.00	My:	-0.01	Mxy:	0.00	M1:	0.00	M2:	-0.01	angle:	-3.7°
SHELL:	1	Surf: 3	Mx:	0.00	My:	0.00	Mxy:	0.00	M1:	0.00	M2:	0.00	angle:	-9.5°
SHELL:	1	Surf: 4	Mx:	0.00	My:	0.00	Mxy:	0.00	M1:	0.00	M2:	0.00	angle:	-9.3°
SHELL:	2	Surf: 1	Mx:	0.00	My:	-0.01	Mxy:	0.00	M1:	0.00	M2:	-0.01	angle:	-3.7°
SHELL:	2	Surf: 2	Mx:	0.00	My:	-0.01	Mxy:	0.00	M1:	0.00	M2:	-0.01	angle:	-3.7°
SHELL:	2	Surf: 3	Mx:	0.00	My:	0.00	Mxy:	0.00	M1:	0.00	M2:	0.00	angle:	-8.7°
SHELL:	2	Surf: 4	Mx:	0.00	My:	0.00	Mxy:	0.00	M1:	0.00	M2:	0.00	angle:	-7.3°
SHELL:	3	Surf: 1	Mx:	-0.01	My:	-0.01	Mxy:	0.00	M1:	-0.01	M2:	-0.01	angle:	-0.8°
SHELL:	3	Surf: 2	Mx:	-0.01	My:	-0.01	Mxy:	0.00	M1:	-0.01	M2:	-0.01	angle:	0.0°
SHELL:	3	Surf: 3	Mx:	0.00	My:	0.00	Mxy:	0.00	M1:	0.00	M2:	0.00	angle:	-10.3°
SHELL:	3	Surf: 4	Mx:	0.00	My:	0.00	Mxy:	0.00	M1:	0.00	M2:	0.00	angle:	-6.2°

# What can be printed about the material behavior?

PRNEASHELL

$$\frac{E t}{1 - \nu^2}$$

$EA_x, EA_y$

in the 4 integr. pts in the plane, for all shell elements

PRNEISHELL

$$\frac{E t^3}{12(1 - \nu^2)}$$

$EI_x, EI_y$

in the 4 integr. pts in the plane, for all shell elements

# STIFFNESS IN THE SHELL ELEMENTS.

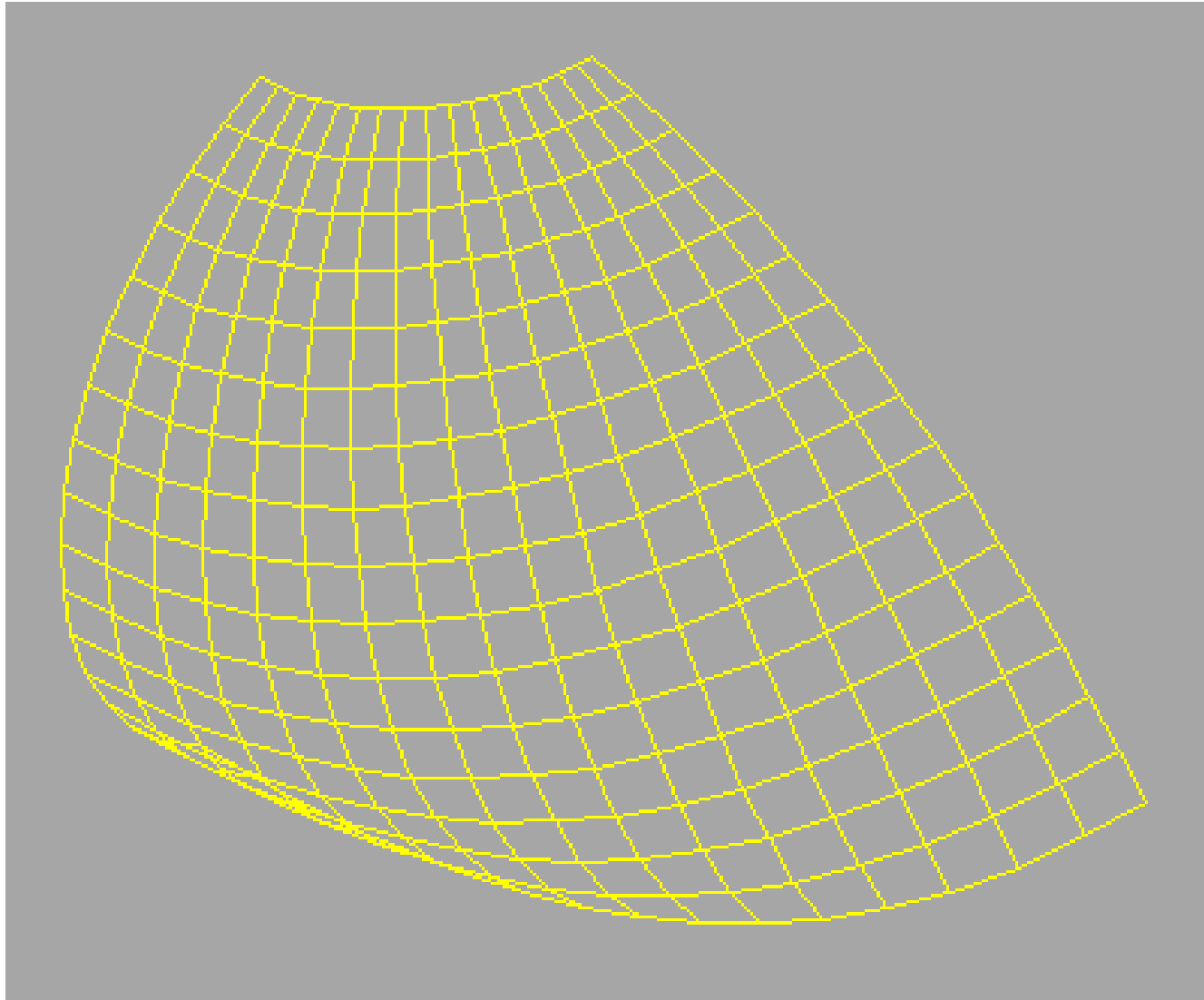
-----

ELEM	NG	EAx	EAy	EIx	EIy
-	-	kN/m	kN/m	kNm <sup>2</sup> /m	kNm <sup>2</sup> /m
1	1	2438151.	2438151.	23.	23.
1	2	2438151.	2438151.	23.	23.
1	3	2438151.	2438151.	23.	23.
1	4	2438151.	2438151.	23.	23.
2	1	2438151.	2438151.	23.	23.
2	2	2438151.	2438151.	23.	23.
2	3	2438151.	2438151.	23.	23.
2	4	2438151.	2438151.	23.	23.

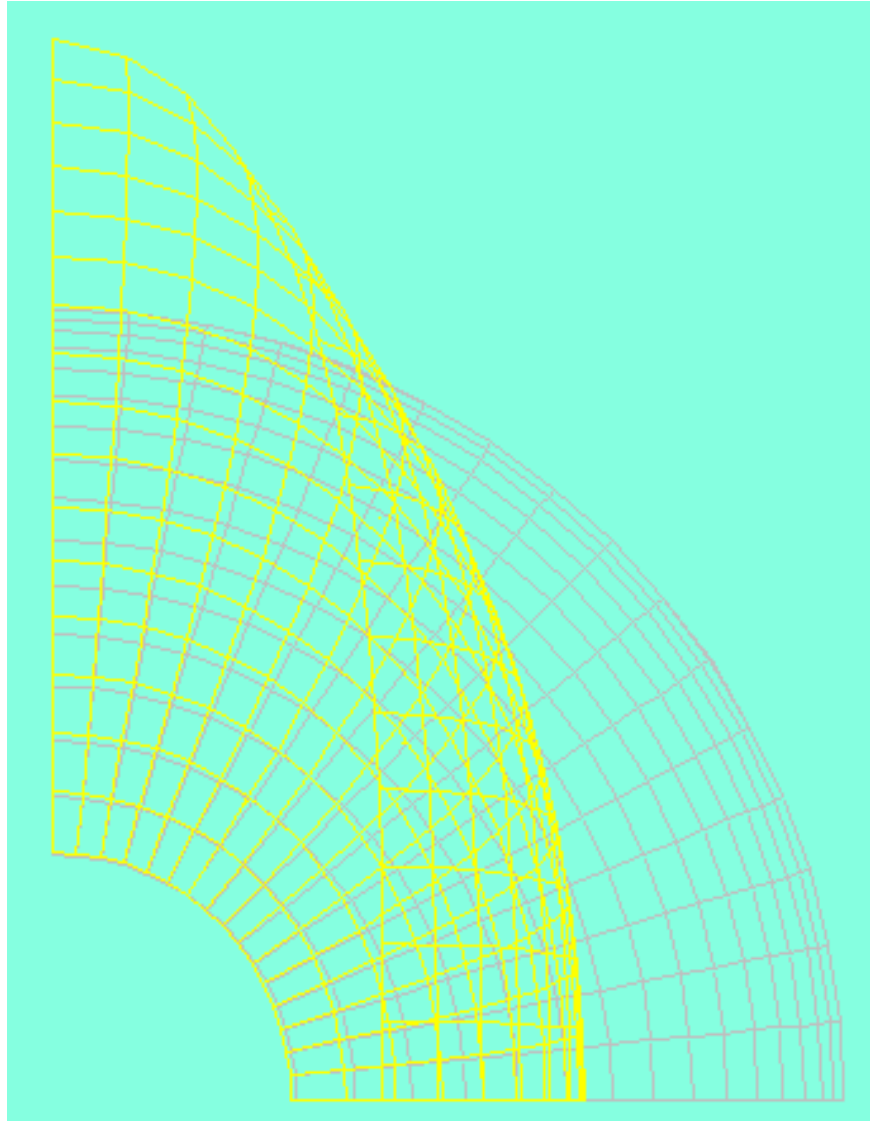


- 1) Degrees of freedom and local axes
- 2) Numerical integration
- 3) Material properties
- 4) Temperature distribution
- 5) Orientation of the rebars
- 6) Spurious modes
- 7) Output
- 8) Examples**

# Deformed Hemispherical Shell

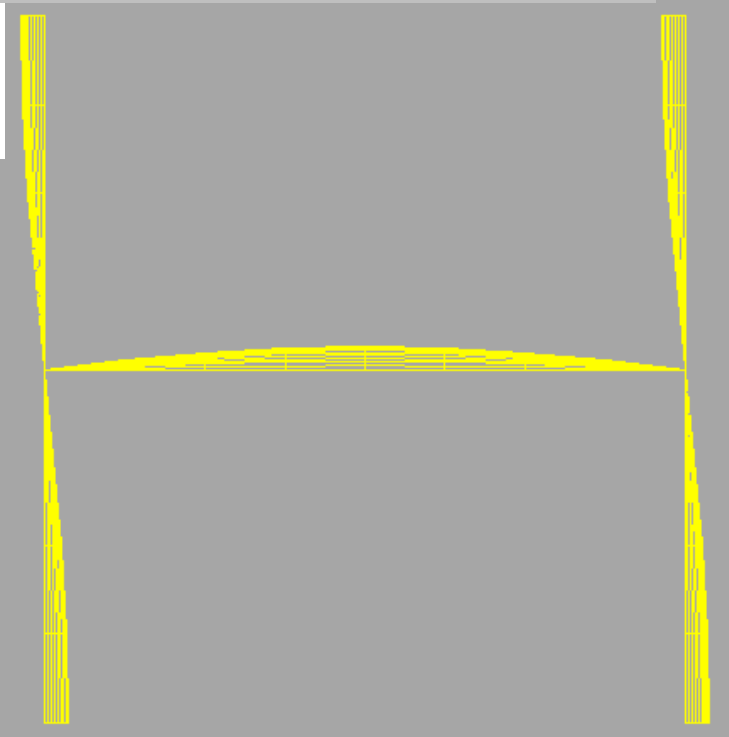
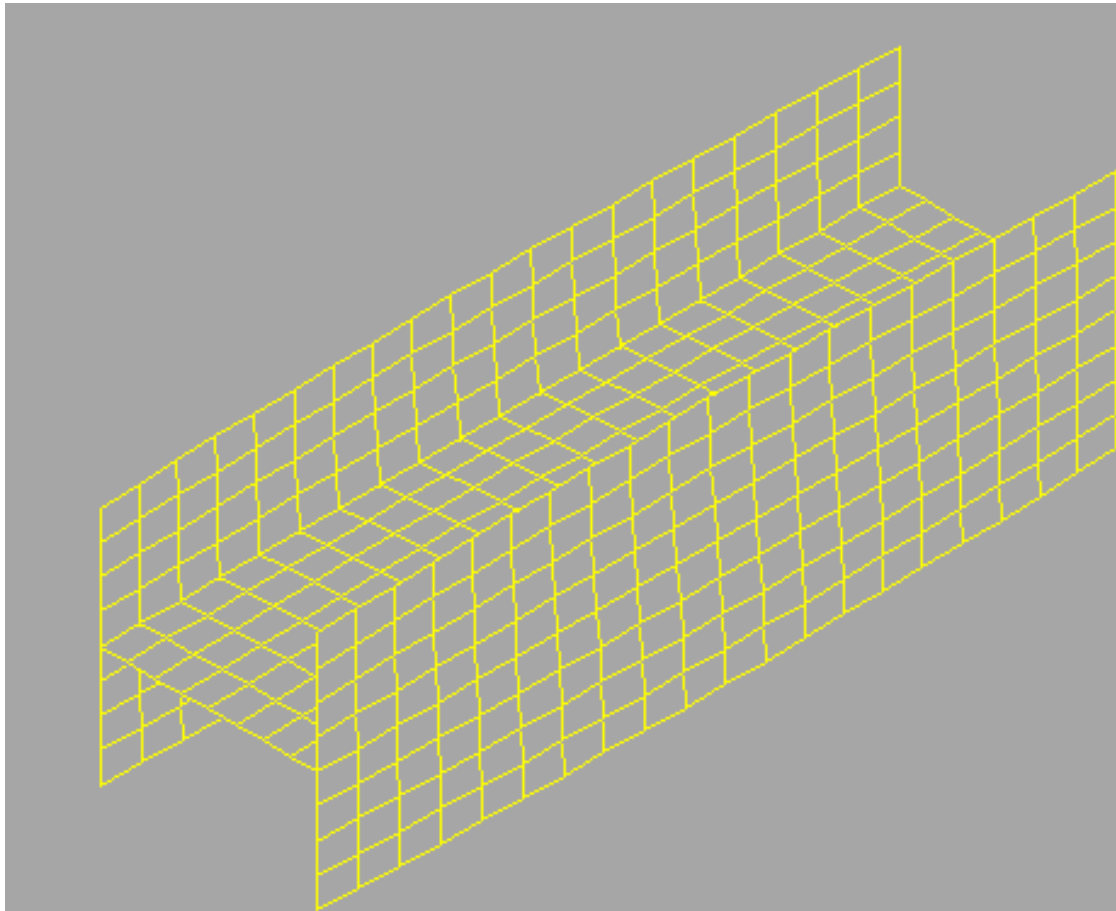


# Initial Geometry and Deformed



# HE 300 AA+

## Initial geometry



## DIAMOND XP

FILE: blog1

NODES: 525

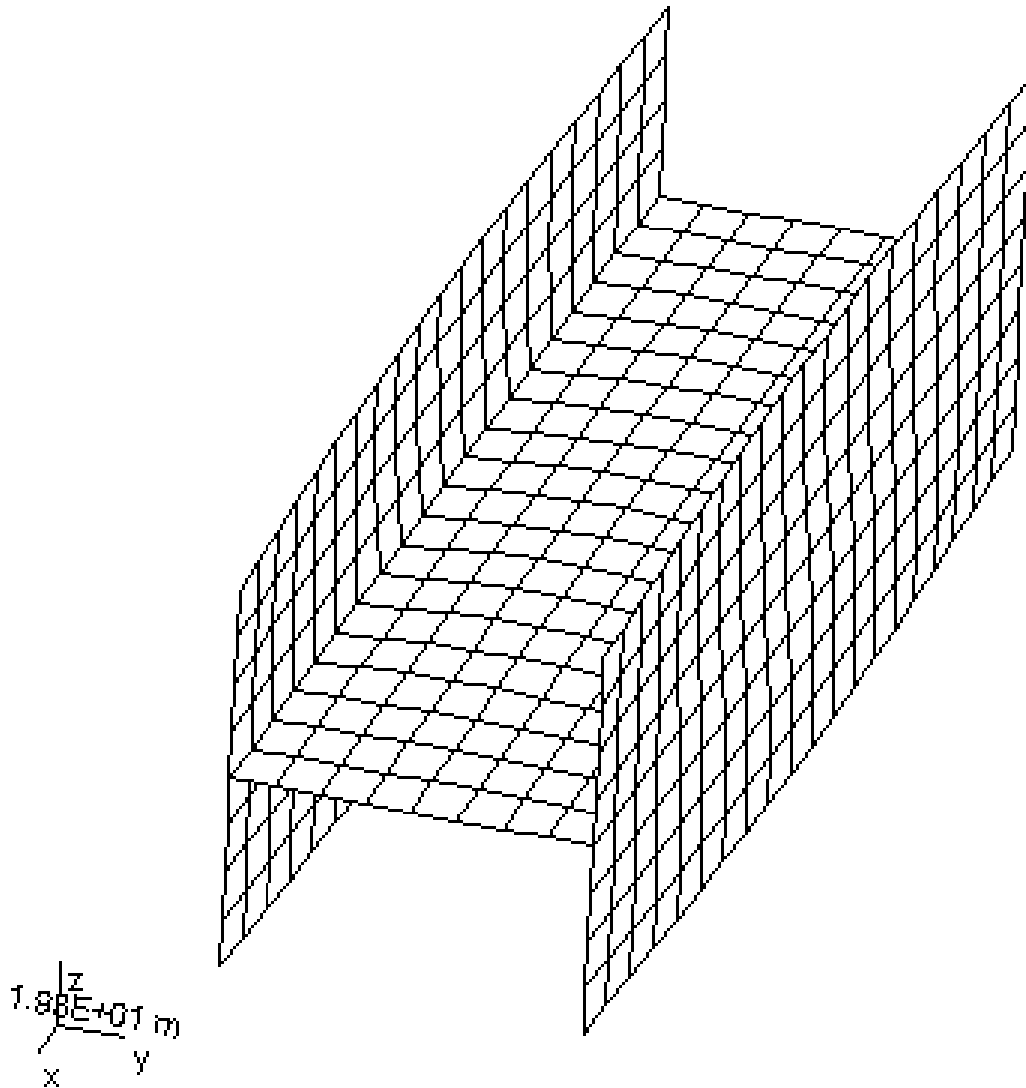
BEAMS: 0

TRUSSES: 0

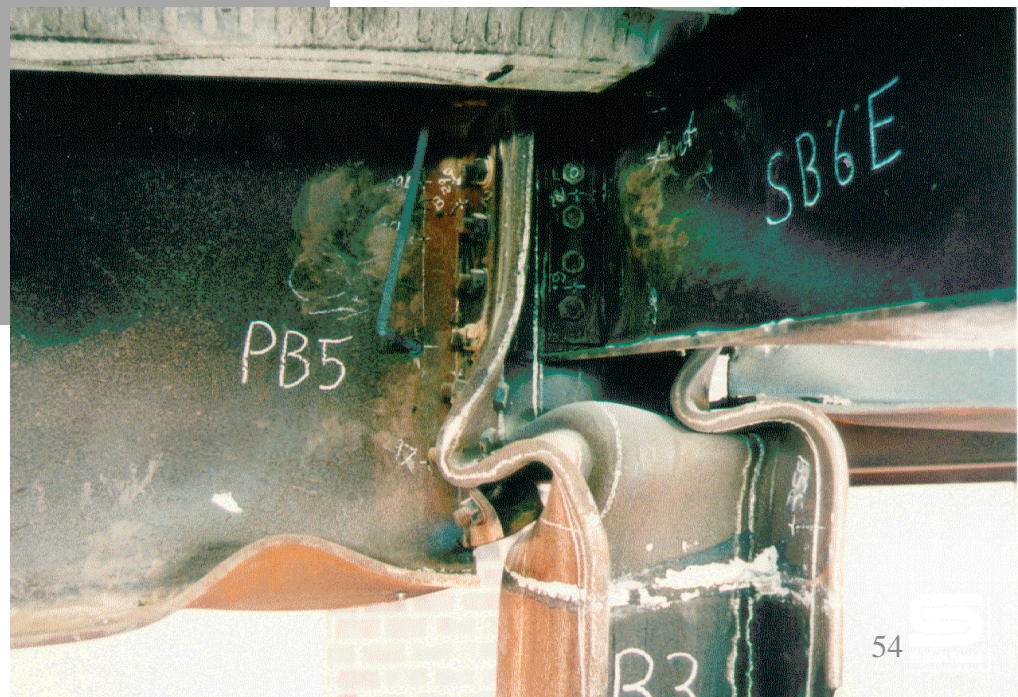
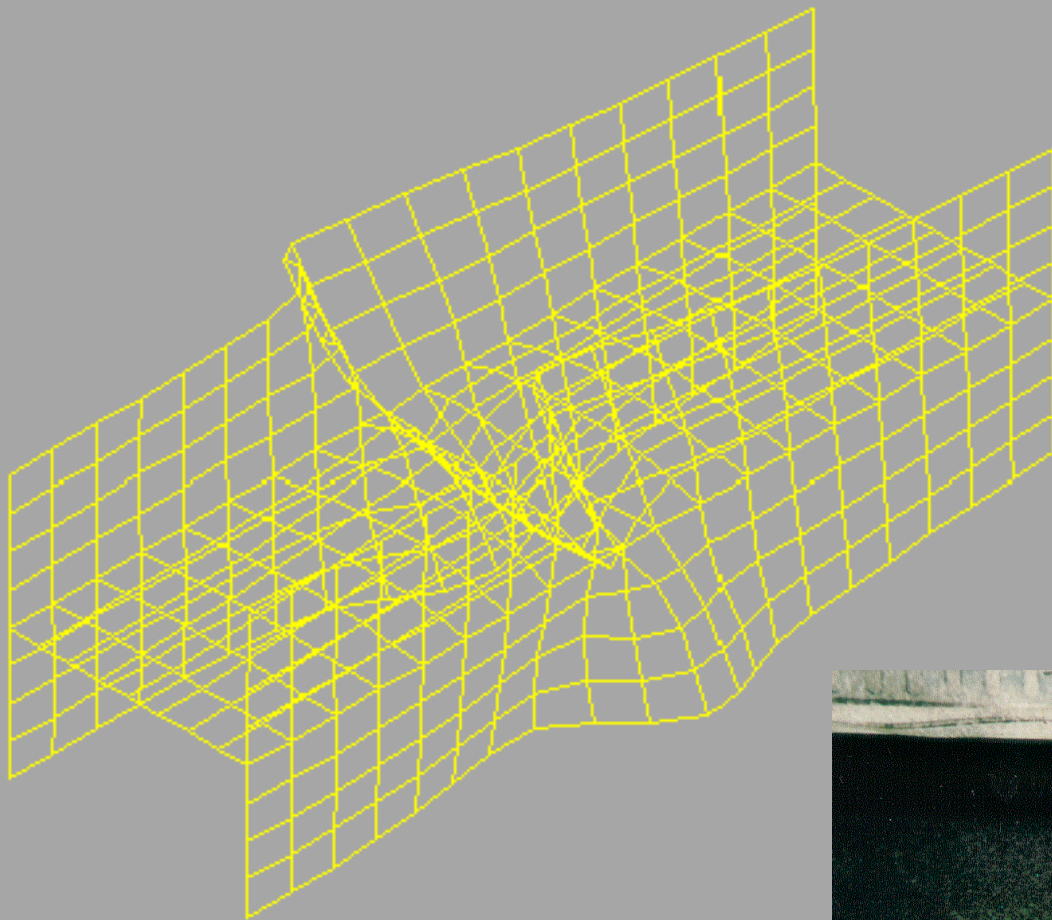
SHELLS: 480

### DISPLACEMENT PLOT

TIME: 2 sec



Heating and shortening  
(no amplification of the displacements in this animation)

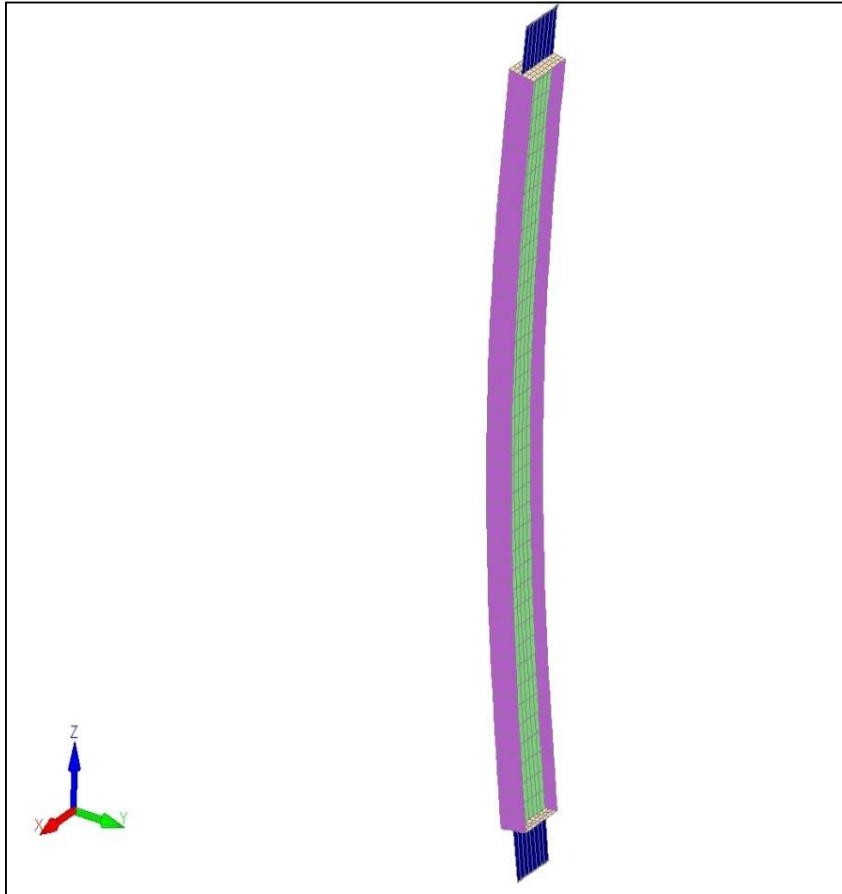


# Numerical simulations vs. Experimental tests

## ■ FIDESC4 Test No 1

Failure Temperature [°C]	SAFIR [°C]	Failure Temperature [°C]	TEST [°C]
571,5		610	

?



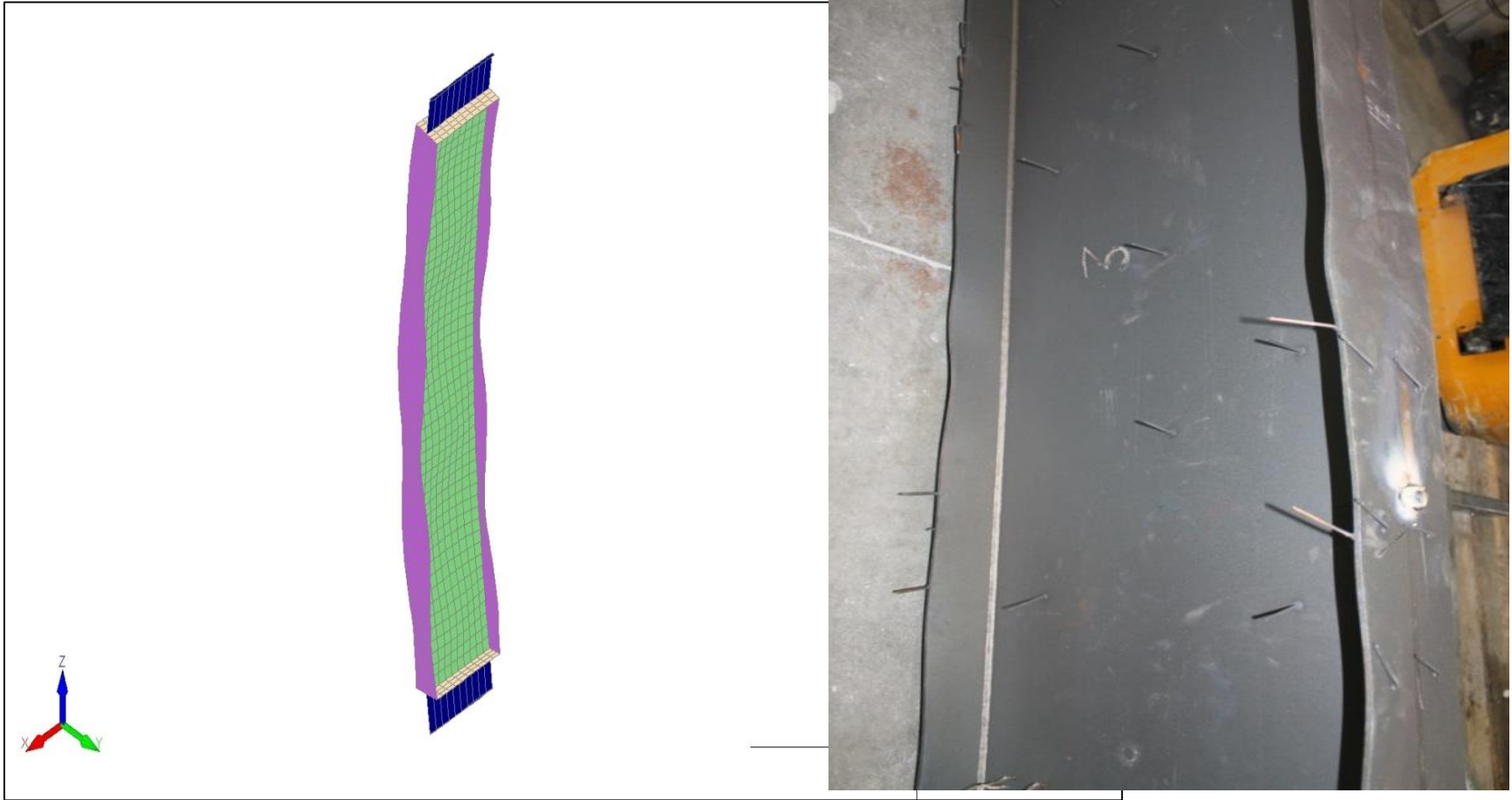


# Numerical simulations vs. Experimental tests

## ■ FISDESC4 Test No 4

?

Failure Temperature [°C]	Failure Temperature [°C]
459	452



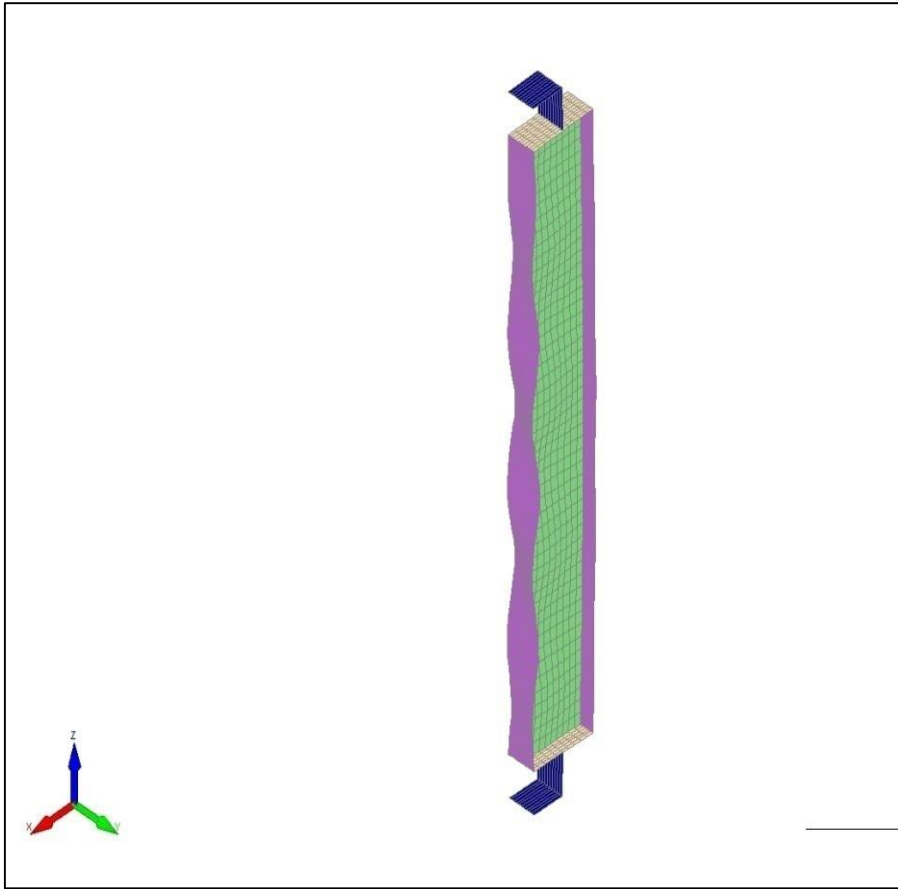


# Numerical simulations vs. Experimental tests

## ■ FISDESC4 Test No 6

?

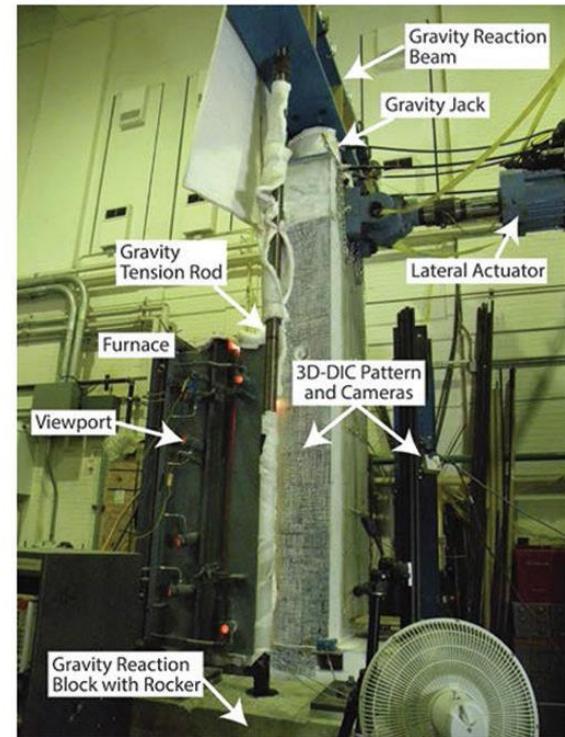
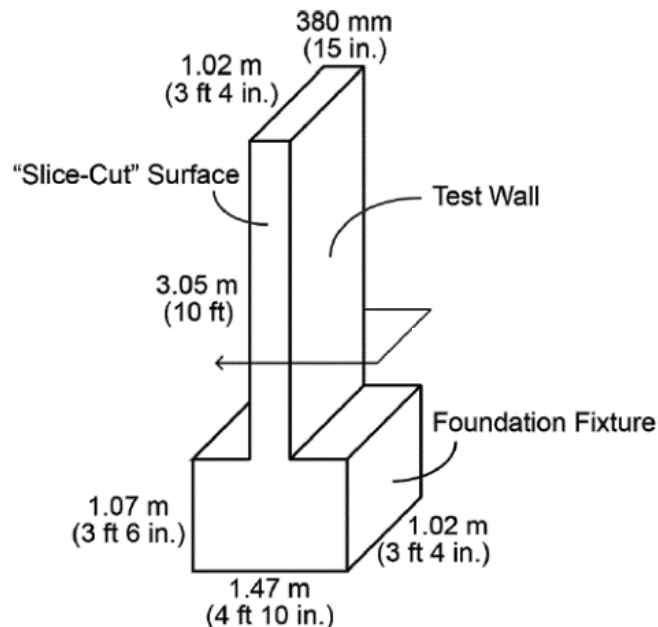
Failure Temperature SAFIR [°C]	Failure Temperature TEST [°C]
531 (cf. Btif+)	530



# Numerical simulations vs. Experimental tests

Test campaign from Notre Dame University

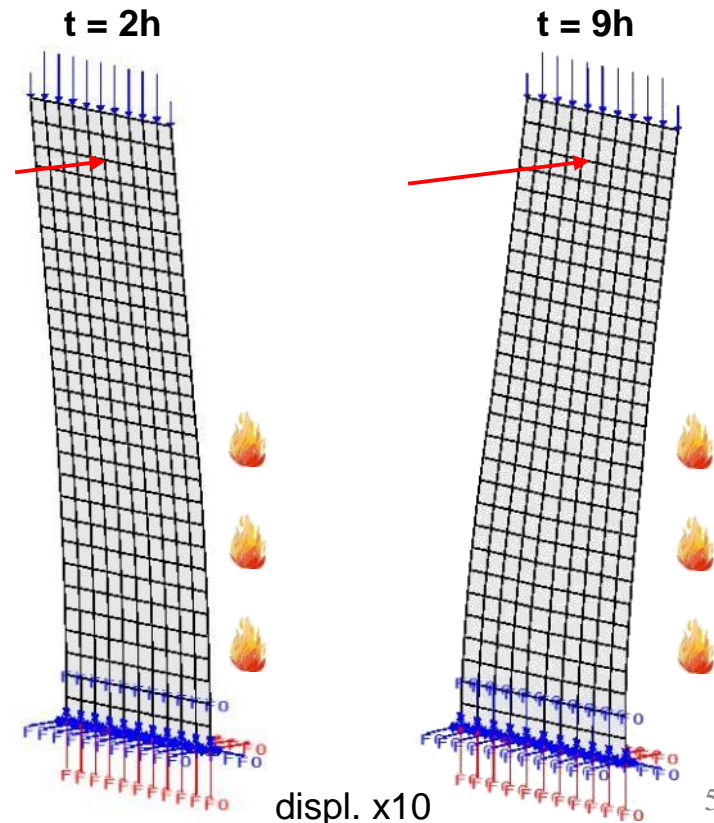
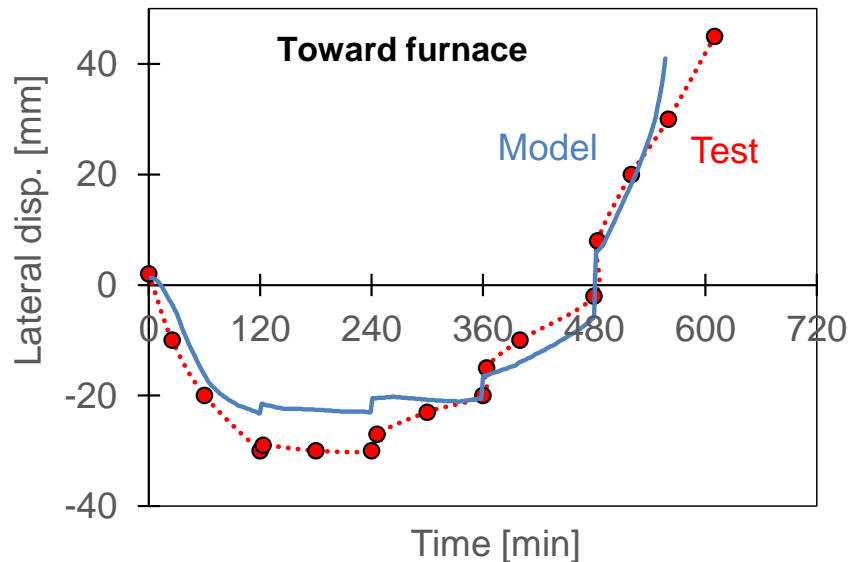
- **Fixed-free RC wall** made of calcareous concrete with  $f_c$  47.1 Mpa
- Test procedure:
  1. **Axial load** of 2400 kN applied at the top
  2. Initial **transverse load** of 36 kN, toward furnace, applied near top
  3. **ASTM E119 fire** starts, **applied on one side** from base to mid-height
  4. **Transverse load stepwise increased** by 22 kN every 2h – test duration 10h



# Numerical simulations vs. Experimental tests

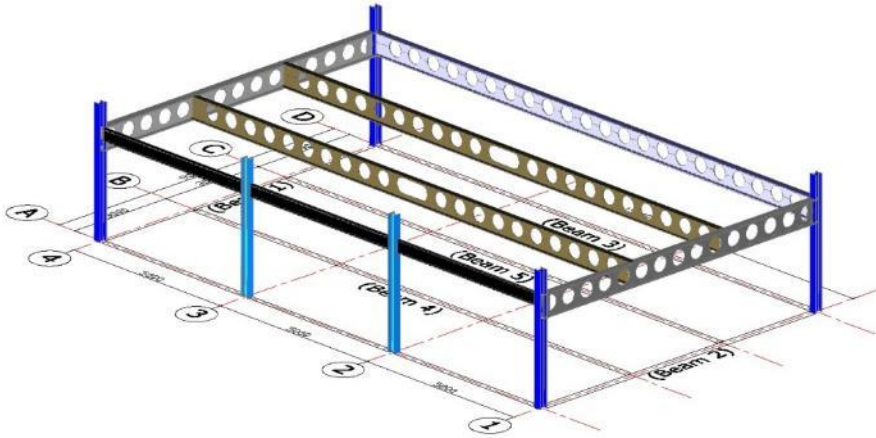
Numerical simulation in SAFIR<sup>1</sup> using the **Shell FE** with multiaxial concrete model

- First, **thermal gradient effect** prevails → moves opposite to the furnace
- Then, **curvature reversal** is captured. Complex combination of:
  - Thermal bowing: bend away from the heat source
  - Transverse load (increased stepwise): bend toward the heat source
  - Transient creep strain on the heated face: bend toward the heat source
  - Shift of neutral axis (affects load eccentricity): bend toward the heat source



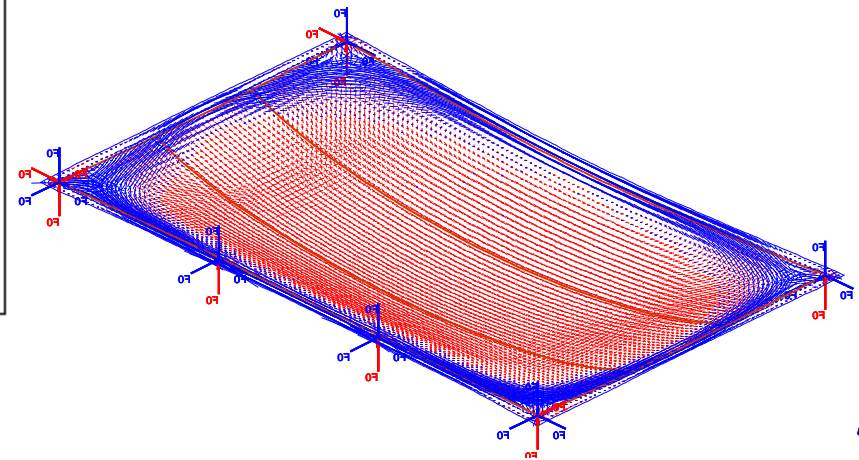
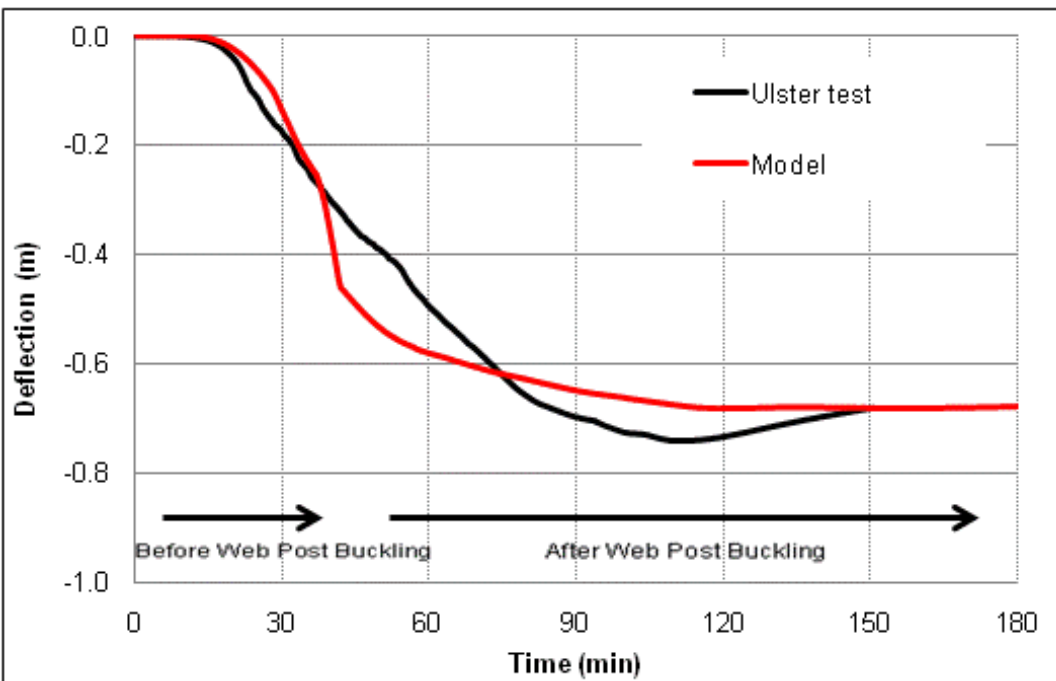
<sup>1</sup>Gernay T, Franssen, JM. (2015) *Fire Safety Journal*.

# Numerical simulations vs. Experimental tests



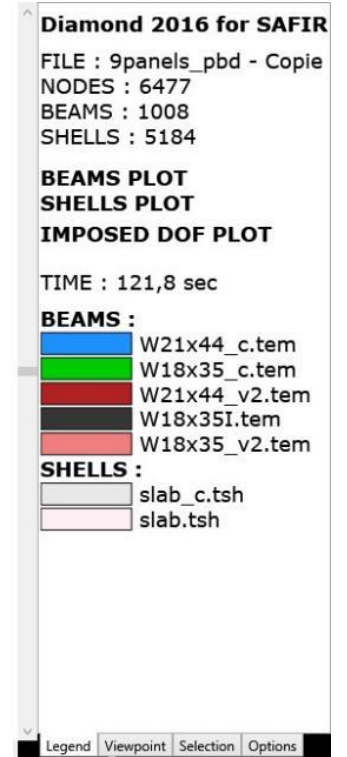
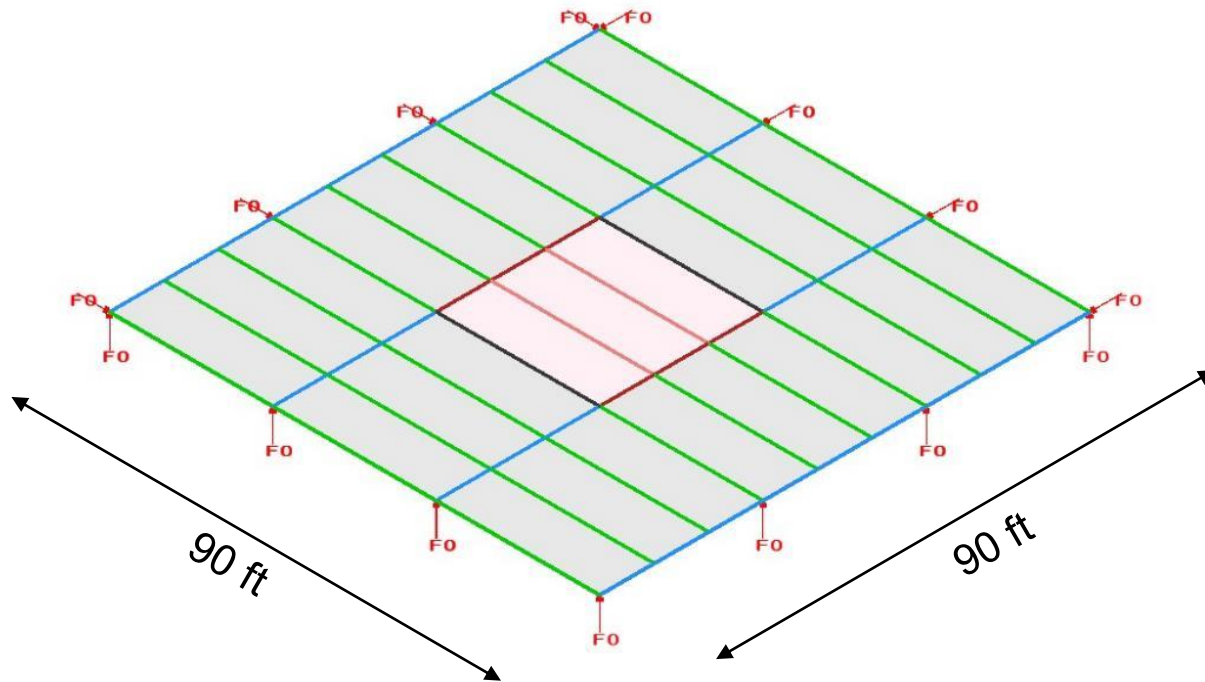


# Numerical simulations vs. Experimental tests

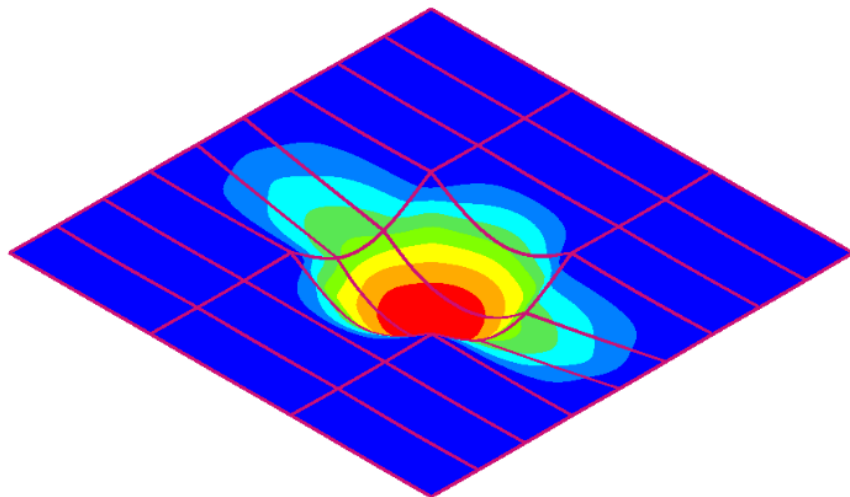


tension

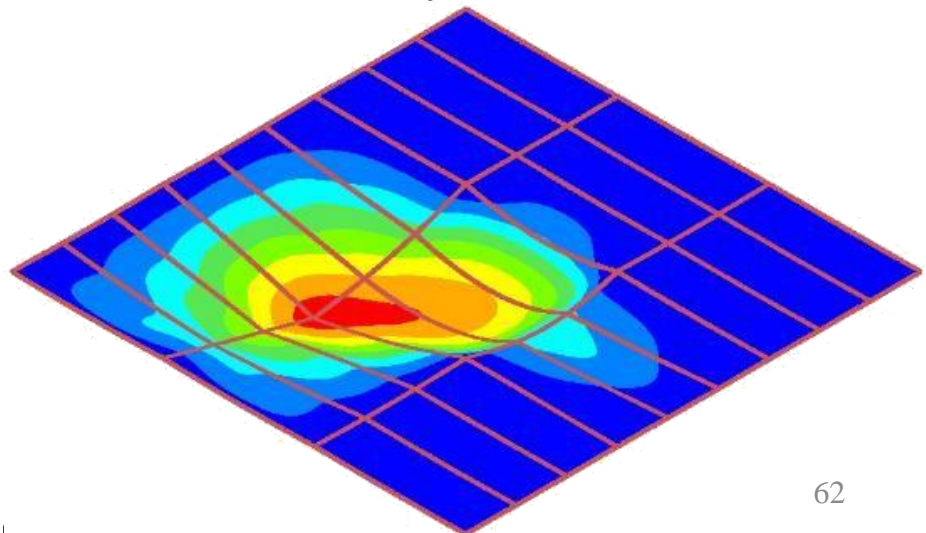
compression



Fire in central bay



Fire in central bay after column loss



# *Thank you*

*For any further information please contact:  
safir@uliege.be*

*Jean Marc Franssen & Thomas Gernay*

